# BOUNDED COHOMOLOGY AND VOLUME RIGIDITY OF HYPERBOLIC 3-MANIFOLDS 

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#### Abstract

We present a rigidity theorem for hyperbolic 3-manifolds $M=$ $\mathbb{H}^{3} / \Gamma$ with a Kleinian surface group $\Gamma$ in terms of the fundamental class $\left[\omega_{M}\right]$ in the bounded cohomology $H_{b}^{3}(M ; \mathbb{R})$. Under some conditions, we show that a homeomorphism $\varphi: M \longrightarrow M$ between hyperbolic 3 -manifolds $M, M^{\prime}$ are bi-Lipschitz if the pseudo-norm $\left\|\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|$ in $H_{b}^{3}(M ; \mathbb{R})$ is less than the volume of a regular ideal simplex in the hyperbolic 3 -space. We see that the separation constant is best possible.


Let $f: M \longrightarrow M^{\prime}$ be a proper degree-one map between oriented hyperbolic 3 -manifolds of finite volume. Gromov and Thurston [Th1, Chapter 6] proved that $f$ is properly homotopic to an isometry if and only if $\operatorname{Vol}(M)=\operatorname{Vol}\left(M^{\prime}\right)$. In the proof, they use the simplicial volume $\|[M]\|$ of $M$, that is, the simplicial norm of the fundamental homology class $[M]$ of $M$. In this paper, we consider the case when $M$ is a hyperbolic 3 -manifold $M$ with the proper homotopy type equivalent to a hyperbolic surface of finite area. Then, since the volume of $M$ is infinite, we can not use the volume as an invariant. So we use the fundamental class in bounded cohomology instead of simplicial volume. The bounded cohomology $H_{b}^{3}(X, \mathbb{R})$ is a homotopy invariant of a topological space $X$ introduced by Gromov [Gr], which has the naturally defined pseudo-norm $\|\cdot\|$, see Section 3 . When $M$ is an oriented hyperbolic 3 -manifold, we consider the 3-cocycle $\omega_{M}: C_{3}(M) \longrightarrow \mathbb{R}$ such that, for any singular 3-simplex $\sigma: \Delta^{3} \longrightarrow M, \omega_{M}(\sigma)$ is the oriented volume of the 3simplex straight $(\sigma)$ obtained by straightening $\sigma$. It is a well know fact in hyperbolic geometry that the supremum norm $\left\|\omega_{M}\right\|$ of $\omega_{M}$ is equal to the volume of a regular ideal simplex $\boldsymbol{v}_{3}=1.01494 \ldots$ in $\mathbb{H}^{3}$. So $\omega_{M}$ represents the fundamental bounded cohomology class $\left[\omega_{M}\right] \in H_{b}^{3}(M, \mathbb{R})$ of $M$ with $\|[\omega]\| \leq \boldsymbol{v}_{3}$.

Throughout this paper, we denote by $\Sigma$ an oriented complete hyperbolic surface of finite area. Possibly $\Sigma$ has parabolic cusps. We only consider the case that any hyperbolic 3-manifolds $M$ admits a proper homotopy equivalence $\iota: \Sigma \longrightarrow M$, which is called a marking of $M$.

We prove the following theorem by using Connecting Lemma (Lemma 5.1) together with Ending Lamination Theorem [Mi, BCM].

Theorem A. Let $M, M^{\prime}$ be hyperbolic 3-manifolds with markings $\iota: \Sigma \longrightarrow M$, $\iota^{\prime}: \Sigma \longrightarrow M^{\prime}$ respectively. Suppose that either the $(+)$ or $(-)$-end $\mathcal{E}$ of $M$ with respect to $\iota(\Sigma)$ is totally degenerate. If

$$
\begin{equation*}
\left\|\iota^{*}\left(\left[\omega_{M}\right]\right)-\iota^{\prime *}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|<\boldsymbol{v}_{3} \tag{0.1}
\end{equation*}
$$

[^0]holds in $H_{b}^{3}(\Sigma, \mathbb{R})$, then there exists a marking and orientation-preserving homeomorphism $\varphi_{0}: M \longrightarrow M^{\prime}$ and a neighborhood $E$ of $\mathcal{E}$ such that $\left.\varphi_{0}\right|_{E}: E \longrightarrow E^{\prime}=$ $\varphi_{0}(E)$ is bi-Lipschitz. In particular, $\varphi_{0}$ defines the bijection between the components of $E_{\text {cusp }}$ and those of $E_{\text {cusp }}^{\prime}$.

Here we say that the end $\mathcal{E}$ is totally degenerate if any genuine sub-end of $\mathcal{E}$ is simply degenerate and set $E_{\text {cusp }}^{(\prime)}=E^{(\prime)} \cap M_{\text {cusp }}^{(\prime)}$. A genuine end of $M$ is an end of $M$ with respect to a maximal cusp of $M$, see Section 1 for the strict definition.

Theorem A says that the fundamental bounded cohomology class keeps the data of the placement of parabolic cusps in a neighborhood of a totally degenerate end. Thus the following corollary is obtained immediately from Theorem A together with Sullivan's Rigidity Theorem [Su].
Corollary B. Under the assumptions in Theorem A including (0.1), suppose moreover that all genuine ends of $M$ are simply degenerate. Then $\varphi$ is properly homotopic to an isometry. In particular, $\iota^{*}\left(\left[\omega_{M}\right]\right)=\iota^{\prime *}\left(\left[\omega_{M^{\prime}}\right]\right)$ in $H_{b}^{3}(\Sigma, \mathbb{R})$.

Now we consider the case when the data of the placement of parabolic cusps in $M$ is known in advance. Then $\varphi$ define the bijection between the genuine ends $\mathcal{E}$ of $M$ and those of $M^{\prime}$, where $\mathcal{E}$ is possibly geometrically finite. Then, by reforming Theorem A, we have the following result which asserts that the structure of $M$ is uniquely determined by the fundamental bounded cohomology class up to biLipschitz.

Theorem C. Let $M$ be an oriented hyperbolic 3-manifold with a marking of $\Sigma$. Suppose that there exists an orientation-preserving homeomorphism $\varphi$ from $M$ to another hyperbolic 3-manifold $M^{\prime}$ inducing a bijection between the components of $M_{\text {cusp }}$ and those of $M_{\text {cusp }}^{\prime}$. If

$$
\begin{equation*}
\left\|\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|<\boldsymbol{v}_{3} \tag{0.2}
\end{equation*}
$$

holds in $H_{b}^{3}(M, \mathbb{R})$, then $\varphi$ is properly homotopic to a bi-Lipschitz map.
Remark 0.1 (Best possibility of separation constant). We refer to Soma [So2, Theorem A], Ohshika-Miyachi [OM, Section 6], Farre [Far1, Corollary 1.5] and so on for precedent results relating to our theorems. In those papers, theorems similar to ours are obtained in suitable settings and under certain conditions with some separation constants as $\boldsymbol{v}_{3}$ in (0.1) or (0.2). However, the practical values of those constants are not presented there and they depend more or less on either the geometric structure on $M$ or the topological type of $\Sigma$. On the other hand, our separation constant is not only concrete but also best possible. In fact, by [So3], if at least one of genuine ends of $M$ is simply degenerate, then $\left\|\left[\omega_{M}\right]\right\|=\boldsymbol{v}_{3}$. In contrast, if $M^{\prime}$ has no simply degenerate ends, then $\left[\omega_{M^{\prime}}\right]=0$ in $H_{b}^{3}\left(M^{\prime}, \mathbb{R}\right)$. So we have

$$
\left\|\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\| \leq\left\|\left[\omega_{M}\right]\right\|+\left\|\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|=\boldsymbol{v}_{3}
$$

but $\varphi$ is not properly homotopic to a bi-Lipschitz map since any simply degenerate end is not bi-Lipschitz to a geometrically finite end.

Remark 0.2 (Volume rigidity). We use volume arguments in the proof of the above theorems, which show that corresponding ends of $E$ and $E^{\prime}$ have the same ending lamination. Then Ending Lamination Theorem implies that $E$ and $E^{\prime}$ are biLipschitz. This means that the latter half of our argument may not be consistent with the title 'volume rigidity' of our paper. It would be possible to prove our
theorems only by using volume arguments as in [So4] together the classical (or standard) theory of hyperbolic geometry by Thurston, for example see [Th1], [Th2, Part 1]. However we relied on the established rigidify theorem by Minsky et al. for ensuring completeness of our proofs.

The fundamental group $\pi_{1}(\Sigma)$ is naturally identified with a Fuchsian group $\Gamma$ in $\mathrm{PSL}_{2}(\mathbb{R})$. We denote by $\mathcal{R}^{(\mathrm{p})}(\Gamma)$ the set of representations $\rho: \Gamma \longrightarrow \mathrm{PSL}_{2}(\mathbb{C})$ which map each parabolic element of $\Gamma$ to a parabolic element of $\mathrm{PSL}_{2}(\mathbb{C})$. The holonomy $\rho_{M}: \Gamma \longrightarrow \mathrm{PSL}_{2}(\mathbb{C})$ of a hyperbolic 3 -manifold $M$ with a marking $\iota: \Sigma \longrightarrow M$ is a discrete and faithful element of $\mathcal{R}^{(\mathrm{p})}(\Gamma)$. We set $\mathcal{R}^{(\mathrm{p})}(\Gamma)=\mathcal{R}(\Gamma)$ if $\Sigma$ has no parabolic cusps. Farre $[\operatorname{Far} 2]$ defined the bounded volume class $[\operatorname{Vol}(\rho)]$ of $\rho$ in $H_{b}^{3}(\Gamma, \mathbb{R})=H_{b}^{3}(\Sigma, \mathbb{R})$. Then $\left[\operatorname{Vol}\left(\rho_{M}\right)\right]$ is equal to $\iota^{*}\left(\left[\omega_{M}\right]\right)$ if $\rho_{M}$ is the holonomy as above. In the case when $\Sigma$ is a closed surface, he presented a rigidity theorem in terms of $[\operatorname{Vol}(\rho)]$ for representations $\rho \in \mathcal{R}(\Gamma)$ such that $\rho(\Gamma)$ contain no parabolic elements. His rigidity theorem also concerns a separating constant but it may depend on the topological type of $\Sigma$. Here we propose the following question asking the existence of a concrete separating constant which is valid in volume rigidity theorems of representations.

Question. Does there exist a concrete constant $v>0$ satisfying the following condition? If it exists, is it best possible?

Let $\rho$ be any element of $\mathcal{R}^{(\mathrm{p})}$ with $\left\|[\operatorname{Vol}(\rho)]-\left[\operatorname{Vol}\left(\rho_{M}\right)\right]\right\|<v$ in $H_{b}^{3}(\Gamma, \mathbb{R})$. If either the $(+)$ or $(-)$-end of $M$ with respect to $\iota(\Sigma)$ is totally degenerate, then $\rho$ is faithful and discrete. Moreover, if the both ends are totally degenerate, then $\rho$ and $\rho_{M}$ are conjugate in $\mathrm{PSL}_{2}(\mathbb{C})$.

## 1. Preliminaries

In this section, we present fundamental definitions and notations in forms suitable to our arguments. Refer to Thurston [Th1], Benedetti and Petronio [BP], Matsuzaki and Taniguchi [MT] and so on for other notations concerning hyperbolic geometry and to Hempel [He] for 3 -manifold topology. For a closed subset $A$ of a metric space $X=(X, d)$ and any $r>0$, the $r$-neighborhood $\{y \in X \mid d(y, A) \leq r\}$ of $A$ is denoted by $\mathcal{N}_{r}(A, X)$ or $\mathcal{N}_{r}(A)$ for short.

Throughout this paper, we suppose that $\Gamma$ is a torsion-free finitely generated Kleinian group, that is, $\Gamma$ is a discrete subgroup of $\mathrm{PSL}_{2}(\mathbb{C})=\operatorname{Isom}{ }^{+}\left(\mathbb{H}^{3}\right)$. Then the quotient map $p: \mathbb{H}^{3} \longrightarrow M=\mathbb{H}^{3} / \Gamma$ is a universal covering and $M$ has a Riemannian metric so that $p$ is locally isometric. Then $M$ is called a hyperbolic 3-manifold.

Fundamental notations and definitions. For a $\mu>0$, the $\mu$-thin part $M_{\operatorname{thin}(\mu)}$ of $M$ is the set of points $x \in M$ such that there exists a non-contractible loop $l$ in $M$ of length $\leq 2 \mu$ and passing through $x$. The complement $M_{\text {thick }(\mu)}=M \backslash \operatorname{Int} M_{\text {thin }(\mu)}$ is called the $\mu$-thick part of M. By the Margulis Lemma [Th1, Corollary 5.10.2], there exists a constant $\mu_{*}>0$ independent of $M$, called a Margulis constant, such that, for any $0<\mu \leq \mu_{*}$, each component of $M_{\operatorname{thin}(\mu)}$ is either an equidistant tubular neighborhood of a simple closed geodesic, called a Margulis tube, in $M$ or a parabolic cusp of type $\mathbb{Z}$ or $\mathbb{Z} \times \mathbb{Z}$. In this paper, we fix the constant $\mu$ with $0<\mu<\mu_{*}$ and set $M_{\text {thick }(\mu)}=M_{\text {thick }}$ and $M_{\text {thin }(\mu)}=M_{\text {thin }}$ for short. Let $M_{\text {cusp }}$ be the union of cuspidal components of $M_{\text {thin }}$ and $M_{\text {tube }}=M_{\text {thin }} \backslash M_{\text {cusp }}$. In other
words, $M_{\text {tube }}$ is the union of Margulis tube components of $M_{\text {thin }}$. We say that the complement $M_{\text {main }}=M \backslash \operatorname{Int} M_{\text {cusp }}$ is the main part of $M$.

As was stated in the introduction, we suppose that $\Sigma$ is an oriented hyperbolic surface of finite area. Let $M$ be an oriented hyperbolic 3-manifold admitting a marking $\iota: \Sigma \longrightarrow M$, which is supposed to be a proper embedding with $\iota\left(\Sigma_{\text {cusp }}\right) \subset M_{\text {cusp }}$. Then each component of $M_{\text {cusp }}$ is a $\mathbb{Z}$-cusp. Let $M_{\text {(cusp) }}$ be the union of components of $M_{\text {cusp }}$ meeting $\iota\left(\Sigma_{\text {cusp }}\right)$ non-trivially. We consider a union $M_{\text {cusp* }}$ of components of $M_{\text {cusp }}$ containing $M_{\text {(cusp) }}$ and set $M_{\text {main* }}=M \backslash M_{\text {cusp* }}$. By Scott-McCullough's Core Theorem [Sc, MC], there exists a compact connected submanifold $C_{\text {main* }}$ of $M_{\text {main* }}$ such that (i) the inclusion $C_{\text {main* }} \subset M_{\text {main* }}$ is a homotopy equivalence, (ii) $C_{\text {main }} \cap V$ is a non-contractible annulus in $\partial V$ for any component $V$ of $M_{\text {cusp* }}$ and (iii) $C_{\text {main* }} \cap V^{\prime}=\emptyset$ for any component $V^{\prime}$ of $M_{\text {cusp }} \backslash M_{\text {cusp* }}$. A connected submanifold $C_{*}$ of $M$ is called a finite core of ( $M, M_{\text {cusp* }}$ ) if $C_{*} \cap M_{\text {main* }}=C_{\text {main* }}$ and $C_{*} \cap V$ is the union of geodesic rays emanating from the points of $C_{\text {main* }} \cap V$ for any component $V$ of $C_{\text {main* }}$.

For a finite core $C_{*}$ of ( $M, M_{\text {main* }}$ ), any component $E$ of $M \backslash \operatorname{Int} C_{*}$ is considered to be a neighborhood of some end $\mathcal{E}$ of $M_{\text {main* }}$. Then $\mathcal{E}$ is called an end of $M$ with respect to the finite core $C_{*}$ or simply an end of $M$ if it does not cause any confusion. Note that $\Sigma_{\mathcal{E}}=C_{*} \cap E$ is a properly embedded incompressible surface in $M$. Any cusp in $E$ of $M$ disjoint from $\Sigma_{\mathcal{E}}$ is called an accidental parabolic cusp of $\mathcal{E}$. We say that $\mathcal{E}$ is an genuine end of $M$ if $\mathcal{E}$ has no accidental parabolic cusps. A genuine end $\mathcal{E}$ is called geometrically finite if the finite core $C_{*}$ can be taken so that $C_{*}$ is locally convex in a neighborhood of $\Sigma_{\mathcal{E}}$ in $M$. According to Bonahon [Bo], if a genuine end $\mathcal{E}$ is not geometrically finite, then there exists a sequence of closed geodesics $\lambda_{n}^{*}$ in $E$ tending toward $\mathcal{E}$ and freely homotopic in $E$ to a simple closed curve $\lambda_{n}$ in $\Sigma_{\mathcal{E}}$. Such a genuine end is called simply degenerate. Note that $E$ is homeomorphic to $\Sigma_{\mathcal{E}} \times[0, \infty)$ when $\mathcal{E}$ is simply degenerate as well as geometrically finite, see [Th1, Theorem 9.4.1] and [Bo, Corollaire C].

If we suppose that $\iota(\Sigma)$ is a degenerate finite core of $M$, then $M$ has two ends with respect to $\iota(\Sigma)$. One of them is called the $(+)$-end of $M$ if it is adjacent to the closure of the component of $M \backslash \iota(\Sigma)$ which is in the $(+)$-side of $\iota(\Sigma)$ with respect to the orientation of $M$, and the other is the $(-)$-end

A finite core $C_{\max }$ of $M$ is maximal if $C_{\max }$ meets all components of $M_{\text {cusp }}$ nontrivially. From the maximality of $C_{\max }$, an end $\mathcal{E}$ of $M$ is genuine if and only if it is an end with respect to $C_{\max }$. For any end $\mathcal{E}_{i}$ of $M$ with respect to a finite core $C_{*}$, a genuine end $\mathcal{E}_{i j}$ is called a genuine sub-end of $\mathcal{E}_{i}$ if a neighborhood of $\mathcal{E}_{i}$ in $M$ contains a neighborhood of $\mathcal{E}_{i j}$. See Figure 1.1. A end of $M$ is totally degenerate if any genuine sub-end of $\mathcal{E}$ is simply degenerate.

## 2. Normalized maps tending toward simply degenerate ends

Suppose that $M$ is a hyperbolic 3-manifold admitting a marking embedding $\iota: \Sigma \longrightarrow M$. In this section, we consider the case that the (+)-end $\mathcal{E}$ of $M$ is totally degenerate. Then there exists a sequence $\left\{f_{n}\right\}_{n=0}^{\infty}$ of pleated maps $f_{n}: \Sigma_{n} \longrightarrow E$ satisfying the following conditions, where $E$ is the neighborhood of $\mathcal{E}$ with respect to $\iota(\Sigma)$. Here we set $E_{\text {main }}=E \cap M_{\text {main }}, E_{\text {thick }}=E \cap M_{\text {thick }}$ and so on.

- For a sufficiently large $R>0, \mathcal{N}_{R}\left(f_{n}\left(\Sigma_{n}\right)\right) \cap \mathcal{N}_{R}\left(f_{n+1}\left(\Sigma_{n+1}\right)\right) \cap E_{\text {main }}=\emptyset(n=$ $0,1, \ldots)$ and $f_{n+1}\left(\Sigma_{n+1}\right)$ is closer to $\mathcal{E}$ compared with $f_{n}\left(\Sigma_{n}\right)$.


Figure 1.1. $\mathcal{E}_{1}, \mathcal{E}_{4}$ are genuine ends with respect to the finite core $C_{*}$. For $i=2,3$, $V_{i}$ is an accidental parabolic cusp of $\mathcal{E}_{i} . \mathcal{E}_{i 1}, \mathcal{E}_{i 2}$ are genuine sub-ends of $\mathcal{E}_{i}$.

- If $f_{n}(\Sigma)$ meets a component $V$ of $E_{\text {tube }}$ non-trivially, then $\Sigma_{n}$ contains a simple geodesic loop $l$ such that $f_{n}(l)$ is the geodesic core of $V$.
- Each $f_{n}$ is unwrapped with respect to any component $V$ of $E_{\text {tube }}$ disjoint from $f_{n}\left(\Sigma_{n}\right)$, that is, $f_{n}$ is properly homotopic to an embedding in $E \backslash V$.
These conditions imply that, if $f_{n}\left(\Sigma_{n}\right) \cap V \neq \emptyset$ for some component $V$ of $E_{\text {tube }}$, then $f_{m}\left(\Sigma_{m}\right) \cap V=\emptyset$ for any $m \neq n$. If necessary passing to a subsequence of $\left\{f_{n}\right\}$, we may also assume the following.
- For any $f_{n}$ and any component $V$ of $E_{\text {cusp }} \backslash E_{\text {(cusp) }}, f_{n}\left(\Sigma_{n}\right) \cap V$ is an annulus, where $E_{\text {(cusp) }}=E \cap M_{\text {(cusp) }}$. See Figure 2.1.


Figure 2.1. $V_{1}, V_{5}$ represent components of $M_{(\text {cusp })}, V_{2}, V_{3}$ components of $E_{\text {tube }}$ with geodesic cores $c_{2}, c_{3}$ and $V_{4}$ an accidental cusp of $\mathcal{E} . \mathcal{N}_{i}=\mathcal{N}_{R}\left(f_{i}\left(\Sigma_{i}\right)\right) \cap E_{\text {thick }}$ for $i=1,2,3 . \mathcal{E}_{1}, \mathcal{E}_{2}$ are simply degenerate sub-ends of $\mathcal{E}$.

The preimage $F_{n}=f_{n}^{-1}\left(E_{\text {thick }}\right)$ is a sub-surface of $\Sigma_{n}$ contained in $\Sigma_{n, \text { thick }}$ such that $\Sigma_{n} \backslash \operatorname{Int} F_{n}$ is a deformation retract of $\Sigma_{n, \text { thin }}$. Modify the Riemannian metric on $E_{\text {thick }}$ in a small neighborhood of $\mathcal{N}_{n}=\mathcal{N}_{R}\left(f_{n}\left(\Sigma_{n}\right)\right) \cap E_{\text {thick }}$ so that $\partial \mathcal{N}_{n}$ is
locally convex in $\mathcal{N}_{n}$. By Freedman-Hass-Scott [FHS], there exists an embedding $h_{n}: F\left(h_{n}\right) \longrightarrow \mathcal{N}_{n}$ which has least area among all piecewise smooth maps $h_{F}^{\prime}$ : $F \longrightarrow \mathcal{N}_{n}$ properly homotopic to $\left.f_{n}\right|_{F_{n}}$ in $E_{\text {thick }}$ and such that each component of $h_{F^{\prime}}\left(\partial F^{\prime}\right)$ is a simple geodesic loop in the Euclidean surface $\partial E_{\text {thick }}$. Let $\widehat{f}_{n}$ : $\widehat{\Sigma}_{n} \longrightarrow E$ be the embedding satisfying the following conditions.

- The domain $\widehat{\Sigma}_{n}$ contains $\widehat{F}_{n}=F\left(h_{n}\right)$ as a sub-surface and $\left.\widehat{f}_{n}\right|_{\widehat{F}_{n}}=\left.h_{n}\right|_{F\left(h_{n}\right)}$.
- Let $C$ be a component of $\widehat{\Sigma}_{n} \backslash \operatorname{Int} \widehat{F}_{n}$. If $\widehat{f}_{n}(C)$ is contained in $M_{\text {(cusp) }}$, then $\widehat{f}_{n}(C)$ is a totally geodesic parabolic cusp. If $\widehat{f}_{n}(C)$ lies in either an accidental cusp of $\mathcal{E}$ or a component $V$ of $E_{\text {tube }}$, then $\widehat{f}_{n}(C)$ is a smoothly embedded ruled annulus in $V$ consisting of shortest arcs in $V$ connecting the components of $\partial V$.
We say that $\widehat{f}_{n}$ is a normalized map associated with $f_{n}$. Then $\widehat{\Sigma}_{n}$ has a piecewise smooth Riemannian metric induced from the hyperbolic metric on $E$ via $\widehat{f}_{n}$. The advantage of normalized maps over pleated maps is that $\widehat{f}_{n}$ are embeddings.

The following lemma is proved immediately from an argument of bounded geometry together with [Th1, Proposition 8.12.1].

Lemma 2.1. The following (1)-(3) hold, where constants means that they are independent of $n$.
(1) There exists a constant $a_{0}>0$ with Area $\left(\widehat{\Sigma}_{n}\right) \leq a_{0}$.
(2) There exists a constant $d_{0}>0$ with $\operatorname{diam}(C) \leq d_{0}$ for any component $C$ of $\widehat{\Sigma}_{n} \backslash \operatorname{Int} \widehat{F}_{n}$.
(3) For any $d>0$, there exists a constant $v_{0}(d)>0$ with $\operatorname{Vol}\left(\mathcal{N}_{d}\left(\widehat{f}_{n}\left(\widehat{\Sigma}_{n}\right)\right)\right)<v_{0}(d)$.

Again by an argument of bounded geometry, there exists a constant $r=r(\Sigma)>0$ such that, for each $n, \widehat{\Sigma}_{n}$ contains a disjoint union $\mathcal{H}\left(\widehat{f}_{n}\right)=\lambda_{1} \sqcup \cdots \sqcup \lambda_{m}$ of mutually disjoint simple loops satisfying the following conditions.

- For each component $\lambda_{j}$ of $\mathcal{H}\left(\widehat{f}_{n}\right)$, length $\widehat{\Sigma}_{n}\left(\lambda_{j}\right)<r$.
- For each annulus component $A$ of $\widehat{\Sigma}_{n} \backslash \operatorname{Int} \widehat{F}_{n}, A \cap \mathcal{H}_{n}$ is the geodesic core of $A$.
- The closure $G$ of each component of $\widehat{\Sigma}_{n} \backslash \mathcal{H}\left(\widehat{f}_{n}\right)$ has bounded geometry and the Euler characteristic - 1 .
We say that $\mathcal{H}\left(\widehat{f}_{n}\right)$ is an $r$-hoop family (for short hoop family) of $\widehat{\Sigma}_{n}$.


## 3. Bounded cohomology and smearing chains on 3-manifolds

We denote by $\Delta^{n}$ a regular $n$-simplex of edge length 1 in the Euclidean $n$-space. Let $C^{*}(X)$ be the dual space of the singular chain-complex $C_{*}(X)$ of a topological space $X$ with real coefficient. Consider the subspace $C_{b}^{*}(X)$ of $C^{*}(X)$ consisting of bounded cochains, that is, $c \in C_{b}^{n}(X)$ means that

$$
\|c\|=\sup \left\{|c(\sigma)| \mid \sigma: \Delta^{n} \longrightarrow X \text { is a singular } n \text {-simplex }\right\}<\infty
$$

Since the coboundary operator $\delta^{n}: C^{n}(X) \longrightarrow C^{n+1}(X)$ satisfies $\delta^{n}\left(C_{b}^{n}(X)\right) \subset$ $C_{b}^{n+1}(X)$, the bounded cochain complex $\left(C_{b}^{*}(X), \delta_{b}^{*}\right)$ with $\delta_{b}^{*}=\left.\delta^{*}\right|_{C_{b}^{*}(X)}$ defines the bounded cohomology

$$
H_{b}^{n}(X, \mathbb{R})=Z_{b}^{n}(X) / B_{b}^{n}(X)
$$

with the pseudo-norm

$$
\|\alpha\|=\inf \left\{\|c\| \mid c \text { is an element of } Z_{b}^{n}(X) \text { with }[c]=\alpha\right\}
$$

for $\alpha \in H_{b}^{n}(X, \mathbb{R})$, where $Z_{b}^{n}(X)=\left(\delta_{b}^{n}\right)^{-1}(0)$ and $B_{b}^{n}(X)=\delta_{b}^{n-1}\left(C_{b}^{n-1}(X)\right)$.
Suppose that $M=\mathbb{H}^{3} / \Gamma$ is a hyperbolic 3 -manifold as in Section 1. Then the quotient map $p: \mathbb{H}^{3} \longrightarrow M$ is a locally isometric universal covering. A singular $k$-simplex $\sigma: \Delta^{k} \longrightarrow M$ is called straight if its lift $\widetilde{\sigma}: \Delta^{k} \longrightarrow \mathbb{H}^{3}$ to $\mathbb{H}^{3}$ is straight, that is, $\widetilde{\sigma}$ is the affine map with respect to the Euclidean structure on $\Delta^{3}$ and the quadratic model on $\mathbb{H}^{3}$. For any singular $k$-simplex $\widetilde{\sigma}: \Delta^{k} \longrightarrow \mathbb{H}^{3}$, let straight $(\widetilde{\sigma})$ : $\Delta^{k} \longrightarrow \mathbb{H}^{3}$ be the straight map with straight $\left(\widetilde{\sigma}\left(v_{j}\right)\right)=\widetilde{\sigma}\left(v_{j}\right)$ for all vertices $v_{j}$ $(j=0,1, \ldots, k)$ of $\Delta^{k}$. We note that the image straight $(\widetilde{\sigma})\left(\Delta^{k}\right)$ is a (possibly degenerate) straight $k$-simplex in $\mathbb{H}^{3}$. For a singular $k$-simplex $\sigma: \Delta^{k} \longrightarrow M$, the map straight ${ }_{M}(\sigma)=p \circ \operatorname{straight}(\widetilde{\sigma}): \Delta^{k} \longrightarrow M$ is called the $k$-simplex obtained by straightening $\sigma$, where $\widetilde{\sigma}: \Delta^{k} \longrightarrow \mathbb{H}^{3}$ is a lift of $\sigma$.

The oriented volume of a $C^{1}$ singular 3 -simplex $\sigma: \Delta^{3} \longrightarrow M$ is defined by

$$
\operatorname{Vol}(\sigma)=\int_{\Delta^{3}} \sigma^{*}\left(\Omega_{M}\right)
$$

where $\Omega_{M}$ is the volume form on $M$. We say that $\sigma$ is non-degenerate if $\operatorname{Vol}(\sigma) \neq 0$, and positive (resp. negative) if $\operatorname{Vol}(\sigma)>0($ resp. $\operatorname{Vol}(\sigma)<0)$.

Let $\omega_{M}$ be the 3 -cocycle on $M$ defined by

$$
\omega_{M}(\sigma)=\operatorname{Vol}\left(\operatorname{straight}_{M}(\sigma)\right)
$$

for any singular 3-simplex $\sigma: \Delta^{3} \longrightarrow M$. Since $\left|\omega_{M}(\sigma)\right|$ is less the volume $\boldsymbol{v}_{3}$ of a regular ideal 3 -simplex in $\mathbb{H}^{3}$ for any singular 3 -simplex $\sigma: \Delta^{3} \longrightarrow M, \omega_{M}$ represents an element $\left[\omega_{M}\right]$ of $H_{b}^{3}(M, \mathbb{R})$ with $\left\|\left[\omega_{M}\right]\right\| \leq \boldsymbol{v}_{3}$. We say that $\left[\omega_{M}\right]$ is the fundamental (bounded cohomology) class of $M$.

For any smooth manifold $N$, let $C^{1}\left(\Delta^{k}, N\right)$ be the topological space of $C^{1}$-maps $\Delta^{k} \longrightarrow N$ with $C^{1}$-topology. We denote by $\mathcal{C}_{k}(N)$ the $\mathbb{R}$-vector space consisting of Borel measures $\mu$ on $C^{1}\left(\Delta^{k}, N\right)$ with the bounded total variation $\|\mu\|<\infty$. An element of $\mathcal{C}_{k}(N)$ is called a $k$-chain. The boundary operator $\partial_{k}: \mathcal{C}_{k}(N) \longrightarrow$ $\mathcal{C}_{k-1}(N)$ is defined naturally. Thus we have the chain complex $\left(\mathcal{C}_{*}(N), \partial_{*}\right)$.

Now we consider the case of $N=M$. Take the base point $x_{0}$ of $\mathbb{H}^{3}$ and suppose that $y_{0}=p\left(x_{0}\right)$ is the base point of $M$. Let $\mu_{\text {Haar }}$ be a left-right invariant Haar measure on $\mathrm{PSL}_{2}(\mathbb{C})$, which is normalized so that, for any bounded Borel subset $U$ of $\mathbb{H}^{3}$,

$$
\begin{equation*}
\mu_{\text {Haar }}\left(\left\{\alpha \in \mathrm{PSL}_{2}(\mathbb{C}) \mid \alpha x_{0} \in U\right\}\right)=\operatorname{Vol}(U) \tag{3.1}
\end{equation*}
$$

From the invariance of $\mu_{\text {Haar }}$, we know that the quotient map $q: \operatorname{PSL}_{2}(\mathbb{C}) \longrightarrow$ $P(M)=\Gamma \backslash \mathrm{PSL}_{2}(\mathbb{C})$ induces the measure $\widehat{\mu}_{\text {Haar }}$ on the quotient space $P(M)$. That is, $\widehat{\mu}_{\text {Haar }}(q(\mathcal{A}))$ is equal to $\mu_{\text {Haar }}(\mathcal{A})$ for any Borel subset $\mathcal{A}$ of $\mathrm{PSL}_{2}(\mathbb{C})$ with $\mathcal{A} \cap$ $\gamma \mathcal{A}=\emptyset$ if $\gamma \in \Gamma \backslash\{1\}$. For any point $x \in \mathbb{H}^{3}$ and $a \in P(M), a \bullet x$ denotes the point of $M$ defined by $p(\alpha x)$ for an $\alpha \in \mathrm{PSL}_{2}(\mathbb{C})$ with $q(\alpha)=a$. Note that the point does not depend on the choice of $\alpha \in q^{-1}(a)$. Thus the map

$$
\bullet: P(M) \times \mathbb{H}^{3} \longrightarrow M
$$

is well-defined. For any singular 3 -simplex $\sigma: \Delta^{3} \longrightarrow \mathbb{H}^{3}$ and $a \in P(M)$, the singular 3 -simplex $a \bullet \sigma: \Delta^{3} \longrightarrow M$ is defined by $p \circ(\alpha \sigma)$ for an $\alpha \in \mathrm{PSL}_{2}(\mathbb{C})$ with $q(\alpha)=a$.

Let $\sigma: \Delta^{3} \longrightarrow \mathbb{H}^{3}$ be a non-degenerate straight 3 -simplex. Suppose that $\operatorname{smear}_{M}(\sigma)$ is the Borel measure on $C^{1}\left(\Delta^{3}, M\right)$ introduced in [Th1, Section 6.1], which satisfies the following conditions.

- The support $\operatorname{supp}\left(\operatorname{smear}_{M}(\sigma)\right)$ is $\{a \bullet \sigma \mid a \in P(M)\}$.
- For any closed non-empty subset $\mathcal{X}$ of $P(M)$,

$$
\begin{equation*}
\operatorname{smear}_{M}(\sigma)(\{a \bullet \sigma \mid a \in \mathcal{X}\})=\widehat{\mu}_{\text {Haar }}(\mathcal{X}) \tag{3.2}
\end{equation*}
$$

We denote the inner center of the straight 3 -simplex $\sigma\left(\Delta^{3}\right)$ in $\mathbb{H}^{3}$ by $o(\sigma)$. For any non-empty almost compact subset $X$ of $M$, the restriction of $\operatorname{smear}_{M}(\sigma)$ to $\{a \bullet \sigma \mid a \in P(M)$ with $a \bullet o(\sigma) \in X\}$ is denoted by $\operatorname{smear}_{X}(\sigma)$. By (3.1) and (3.2), its total variation is

$$
\begin{equation*}
\left\|\operatorname{smear}_{X}(\sigma)\right\|=\operatorname{Vol}(X) \tag{3.3}
\end{equation*}
$$

In particular, $\operatorname{smear}_{X}(\sigma)$ is an element of $\mathcal{C}_{3}(M)$. Set $\sigma_{-}=\rho \circ \sigma$ for an orientationreversing isometry $\rho$ on $\mathbb{H}^{3}$ with $\rho(o(\sigma))=o(\sigma)$. Consider the element $z_{X}(\sigma)$ of $\mathcal{C}_{3}(M)$ defined by

$$
\begin{equation*}
z_{X}(\sigma)=\frac{1}{2}\left(\operatorname{smear}_{X}(\sigma)-\operatorname{smear}_{X}\left(\sigma_{-}\right)\right) \tag{3.4}
\end{equation*}
$$

Then, by (3.2) and (3.3), we have $\left\|z_{X}(\sigma)\right\|=\operatorname{Vol}(X)$ and

$$
z_{X}(\sigma)(\{a \bullet \sigma \mid a \in P(M) \text { with } a \bullet o(\sigma) \in X\})=\frac{1}{2} \operatorname{Vol}(X)
$$

For a Borel measure $\omega$ on $C^{1}\left(\Delta^{3}, M\right)$, let $\operatorname{supp}^{(2)}(w)$ be the subset of $C^{1}\left(\Delta^{2}, M\right)$ defined by

$$
\begin{equation*}
\operatorname{supp}^{(2)}(w)=\left\{\left.\tau\right|_{D} \mid \tau \in \operatorname{supp}(w) \text { and } D \in\left(\Delta^{3}\right)^{(2)}\right\} \tag{3.5}
\end{equation*}
$$

where $\left(\Delta^{3}\right)^{(2)}$ is the set of 2-faces of $\Delta^{3}$. By the definition, $\operatorname{supp}\left(\partial_{3} w\right) \subset \operatorname{supp}^{(2)}(w)$.
Let $\left\{\widehat{f}_{n}\right\}_{n=0}^{\infty}$ be the sequence of normalized maps $\widehat{f}_{n}: \widehat{\Sigma}_{n} \longrightarrow E$ given in Section 2. For any $m, n$ with $m<n$, we denote by $E\left(\widehat{f}_{m}, \widehat{f}_{n}\right)$ the closure of the component of $E \backslash \widehat{f}_{m}\left(\widehat{\Sigma}_{m}\right) \cup \widehat{f}_{n}\left(\widehat{\Sigma}_{n}\right)$ bounded by $f_{m}\left(\widehat{\Sigma}_{m}\right) \cup \widehat{f}_{n}\left(\widehat{\Sigma}_{n}\right)$.
Lemma 3.1. Under the notation as above, let $\widehat{X}=E\left(\widehat{f}_{m}, \widehat{f}_{n}\right)$. Then $\operatorname{supp}\left(\partial_{3} z_{\widehat{X}}(\sigma)\right)$ is contained in $\operatorname{supp}^{(2)}\left(z_{\mathcal{N}_{2}(\partial \widehat{X}, M)}(\sigma)\right)$ and $\left\|\partial_{3} z_{\widehat{X}}(\sigma)\right\|<8 v_{0}(2)$ holds, where $v_{0}(2)$ is the constant given in Lemma 2.1(3).
Proof. The volume of any (real) straight 3 -simplex $\Delta$ in $\mathbb{H}^{3}$ is less than $\boldsymbol{v}_{3}=$ $1.014916 \ldots$. On the other hand, since the volume of a 3 -ball in $\mathbb{H}^{3}$ of radius one is $\pi(\sinh 2-2)=5.11093 \ldots$, the radius of the inscribed ball in $\Delta$ is less than one. Let $D$ be any element of $\left(\Delta^{3}\right)^{(2)}$. For any $a \bullet \sigma$ with $a \bullet o(\sigma) \in \widehat{X}$, there exists $b \in P(M)$ with $b \bullet o\left(\sigma_{-}\right) \in \mathcal{N}_{2}(\widehat{X}, M)$ and such that $\left.a \bullet \sigma\right|_{D}=\left.b \bullet \sigma_{-}\right|_{D}$. See Figure 3.1. Similarly, we have $\left.a \bullet \sigma_{-}\right|_{D}=\left.b \bullet \sigma\right|_{D}$. In general, we can not expect that $b \bullet o\left(\sigma_{-}\right)$is contained in $\widehat{X}$. However, if $a \bullet o(\sigma) \in \widehat{X} \backslash \mathcal{N}_{2}(\partial \widehat{X}, M)$, then $b \bullet o\left(\sigma_{-}\right)$ is an element of $\widehat{X}$. These facts imply that $\operatorname{supp}\left(\partial_{3} z_{\widehat{X}}(\sigma)\right) \subset \operatorname{supp}^{(2)}\left(z_{\mathcal{N}_{2}(\partial \widehat{X}, M)}\right)$. Since $\partial \widehat{X}=\widehat{f}_{m}\left(\widehat{\Sigma}_{m}\right) \cup \widehat{f}_{n}\left(\widehat{\Sigma}_{n}\right)$, we have by Lemma 2.1 (3)

$$
\left\|z_{\mathcal{N}_{2}(\partial \widehat{X}, M)}(\sigma)\right\|=\operatorname{Vol}\left(\mathcal{N}_{2}\left(\widehat{f}_{m}\left(\widehat{\Sigma}_{m}\right) \cup \widehat{f}_{n}\left(\widehat{\Sigma}_{n}\right)\right)\right)<2 v_{0}(2)
$$

Since $\Delta^{3}$ has four 2-faces, $\left\|\partial_{3} z_{\widehat{X}}(\sigma)\right\|<4 \cdot 2 v_{0}(2)=8 v_{0}(2)$.
Since the image $\tau\left(\Delta^{3}\right)$ of any element $\tau=a \bullet \sigma \in \operatorname{supp}\left\{z_{\widehat{X}}(\sigma)\right\}$ has 'long tails', $\tau\left(\Delta^{3}\right)$ is not necessarily contained in $\widehat{X}$ even if $a \bullet o(\sigma)$ is an element of $\operatorname{Int} \widehat{X}$ such that $\operatorname{dist}(a \bullet o(\sigma), \partial \widehat{X})$ is large. So we sometimes need to treat the body (inner part) and tails (outer part) of $\tau\left(\Delta^{3}\right)$ separately as in the next section.


Figure 3.1

Remark 3.2. Let $X$ be a topological space and $C_{*}^{\text {sing }}(X)$ the singular chain group of $X$ with real coefficients. The Gromov norm of an element $c=\sum_{i=1}^{n} r_{i} \sigma_{i}$ of $C_{q}^{\text {sing }}(X)$ is given by $\|c\|=\sum_{i=1}^{n}\left|r_{i}\right|$. Let $C_{*}^{l_{1}}(X)$ be the norm completion of $C_{*}^{\text {sing }}(X)$. Thus $C_{*}^{l_{1}}(X)$ is a Banach space consisting of elements $c=\sum_{i=1}^{\infty} r_{i} \sigma_{i}$ with $\|c\|=\sum_{i=1}^{\infty}\left|r_{i}\right|<\infty$. If an element $c$ of $C^{l_{1}}(M)$ is a linear combination $\sum_{i=1}^{\infty} r_{i} \sigma_{i}$ of straight 3 -simplices $\sigma_{i}: \Delta^{3} \longrightarrow M$, then $c$ is identified with the element $\sum_{i=1}^{\infty} r_{i} \delta_{\sigma_{i}}$ of $\mathcal{C}_{3}(M)$, where $\delta_{\sigma_{i}}$ is the Dirac measure on $C^{1}\left(\Delta^{3}, M\right)$ at $\sigma_{i}$. Then the Gromov norm $\sum_{i=1}^{\infty}\left|r_{i}\right|$ of $c$ is equal to the total variation of $\sum_{i=1}^{\infty} r_{i} \delta_{\sigma_{i}}$. There exists a sequence $\left\{c_{n}\right\}$ of locally finite elements in $C_{*}^{l_{1}}(X)$ with $c_{n}=\sum_{i=1}^{\infty} r_{i} \sigma_{i}^{n}$ consisting of straight 3 -simplices $\sigma_{i}^{n}$ with

$$
\left|\operatorname{Vol}\left(\sigma_{i}^{n}\right)-\operatorname{Vol}(\sigma)\right|<\frac{1}{n}
$$

and such that $\left\{c_{n}\right\}$ weakly converges to $z_{X}(\sigma)$ and $\left\{\partial_{3} c_{n}\right\}$ weakly converges to $\partial_{3} z_{X}(\sigma)$. For example see the map $\mathcal{A}_{*}$ in [So1, Section 3]. In our arguments below, we may use the usual locally finite singular 3 -chain $c_{n}$ in $C^{l_{1}}(X)$ with sufficiently large $n$ instead of $z_{X}(\sigma)$ if necessary.

## 4. Linear isoperimetric inequality modulo hoop families

First we define a subdivision of hyperbolic straight simplices. Let $\Delta$ be any straight 3 -simplex in $\mathbb{H}^{3}$ with real vertices $v_{0}, v_{1}, v_{2}, v_{3}$ and $\operatorname{Vol}(\Delta)>1$. Consider the inscribed sphere $S(\Delta)$ of $\Delta$ and $S_{i}(i=0,1,2,3)$ the round sphere in $\mathbb{H}^{3}$ centered at $v_{i}$ and tangent to $S(\Delta)$. Each $S_{i}$ intersects three edges of $\Delta$. Let $T_{i}$ be the totally geodesic triangle in $\Delta$ with the three intersection points as its vertices. We denote by $\Delta_{i, \text { out }}$ the closure of the component of $\Delta \backslash T_{0} \cup \cdots \cup T_{3}$ containing $v_{i}$ and by $\Delta_{\text {inn }}$ the closure of $\Delta \backslash \Delta_{\text {out }}$, where $\Delta_{\text {out }}=\Delta_{0, \text { out }} \cup \cdots \cup \Delta_{3, \text { out }}$. We say that $\Delta_{\text {inn }}$ and $\Delta_{\text {out }}$ are the inner and outer parts of $\Delta$, respectively. See Figure 4.1. For any small positive number $\xi$, say $\xi<1 / 100$, there exists a simplicial triangulation $\tau(\Delta, \xi)$ of $\Delta$ satisfying the following conditions, where $\tau(\Delta, \xi)^{(i)}$ denotes the subset of $\tau(\Delta, \xi)$ consisting of $i$-simplices.


Figure 4.1

- Each element of $\tau(\Delta, \xi)^{(3)}$ is a straight simplex.
- For any $e \in \tau(\Delta, \xi)^{(1)}$ with $e \subset \Delta_{\mathrm{inn}}, \delta(\xi) \leq \operatorname{length}_{\Delta}(e) \leq \xi$, where $\delta(\xi)$ is a uniform constant with $0<\delta(\xi)<\xi$.
- Each $T_{i}$ is the underlying space of a subcomplex of $\bigcup_{i=0}^{2} \tau(\Delta, \xi)^{(i)}$. Each edge $\alpha_{i j}$ of $T_{i}$ is evenly divided by $\left.\tau(\Delta, \xi)^{(0)}\right|_{\alpha_{i j}}$.
- For each edge $\beta_{j k}$ of $\Delta$ connecting $v_{j}$ with $v_{k}, \beta_{j k} \cap \Delta_{\mathrm{inn}}$ is evenly divided by $\left.\tau(\Delta, \xi)^{(0)}\right|_{\beta_{j k} \cap \Delta_{\mathrm{inn}}}$.
- $\Delta_{\text {out }} \backslash\left(\left\{v_{0}, \ldots, v_{3}\right\} \cup T_{1} \cup \cdots \cup T_{4}\right)$ contains no elements of $\tau(\Delta, \xi)^{(0)}$.

See Figure 4.2. In fact, such triangulations can be obtained from a fixed simplicial


Figure 4.2. The restriction of $\tau(\Delta, \xi)$ to a 2-face $\Delta_{j}^{2}$ of $\Delta$ in the Klein model. The inner hexagonal part is $\Delta_{j}^{2} \cap \Delta_{\text {inn }}$.
triangulation $\tau\left(\Delta_{\infty}, \xi\right)$ on a regular ideal 3 -simplex $\Delta_{\infty}$ in $\mathbb{H}^{3}$ satisfying the five conditions as above, where the ideal simplices of $\Delta_{\infty}$ are regarded as elements
of $\tau\left(\Delta_{\infty}, \xi\right)^{(0)}$. Since $\boldsymbol{v}_{3}-0.015<\operatorname{Vol}(\Delta)<\boldsymbol{v}_{3}$, there exists a $\kappa$-bi-Lipschitz map $\alpha: \Delta_{\infty, \text { inn }} \longrightarrow \Delta_{\text {inn }}$ for some uniform constant $\kappa$ close to one such that $\alpha\left(\left.\tau\left(\Delta_{\infty}, \xi\right)^{(0)}\right|_{\Delta_{\infty, \text { inn }}}\right)$ extends to a triangulation $\left.\tau(\Delta, \xi)\right|_{\Delta_{\text {inn }}}$ on $\Delta_{\text {inn }}$ satisfying the required conditions. We set $\tau(\Delta, \xi)_{\text {inn }}=\left.\tau(\Delta, \xi)\right|_{\Delta_{\text {inn }}}$ and $\tau(\Delta, \xi)_{\text {out }}=\left.\tau(\Delta, \xi)\right|_{\Delta_{\text {out }}}$.

Suppose that $\sigma^{\prime} \in \operatorname{supp}\left(\operatorname{smear}_{M}(\sigma)\right)$ and $\sigma_{-}^{\prime} \in \operatorname{supp}\left(\operatorname{smear}_{M}\left(\sigma_{-}\right)\right)$are 3-simplices with $\left.\sigma^{\prime}\right|_{\Delta_{j}^{2}}=\left.\sigma_{-}^{\prime}\right|_{\Delta_{j}^{2}}$ for some 2-face $\Delta_{j}^{2}$ of $\Delta$. Then, for any element $D$ of $\left.\tau(\Delta, \xi)^{(2)}\right|_{\Delta_{j}^{2}}$, we have

$$
\begin{equation*}
\left.\sigma^{\prime}\right|_{D}-\left.\sigma_{-}^{\prime}\right|_{D}=0 \tag{4.1}
\end{equation*}
$$

Let $\left\{\widehat{f}_{n}\right\}_{n=0}^{\infty}$ be the sequence of normalized maps $\widehat{f}_{n}: \widehat{\Sigma}_{n} \longrightarrow E$ given in Section 2. For simplicity, we only consider here the pair $\widehat{f}_{0}, \widehat{f}_{1}$. Our argument works for any pair $\widehat{f}_{m}, \widehat{f}_{n}$ with $m<n$. By Lemma 2.1 (2), one can define an (ideal) triangulation $\tau_{i}(i=0,1)$ on $\widehat{\Sigma}_{i}$ satisfying the following conditions, where $\mathcal{H}\left(\widehat{f_{i}}\right)(i=1,0)$ is a hoop family of $\widehat{\Sigma}_{i}$.
(T1) Each element $v$ of $\tau_{i}^{(0)}$ is either a point of $\mathcal{H}\left(\widehat{f_{i}}\right)$ or an ideal point of $\widehat{\Sigma}_{i}$. See Figure 4.3.
(T2) $\bigcup \tau_{i}^{(1)}$ contains $\mathcal{H}\left(\widehat{f_{i}}\right)$.
(T3) For any component $l$ of $\mathcal{H}\left(\widehat{f}_{i}\right), l \cap \bigcup \tau_{i}^{(0)}$ consists of just two points.
(T4) The cardinality of $\tau_{i}$ is uniformly bounded.
(T5) There exists a uniform constant $d_{1}>0$ such that the $d_{1}$-neighborhood of any point $x$ of $F\left(\widehat{f}_{i}\right)=\widehat{f}_{i}^{-1}\left(E_{\text {thick }}\right)$ contained in $\operatorname{star}(v)$ for some $v \in \tau_{i}^{(0)}$, where $\operatorname{star}(v)$ is the union $\bigcup_{\alpha} \operatorname{Int} D_{\alpha}$ for all elements $D_{\alpha}$ of $\tau_{i}$ with $v$ as a common vertex.
We say that $\tau_{i}$ is a normalized triangulation on $\widehat{\Sigma}_{i}$ with respect to $\mathcal{H}\left(\widehat{f_{i}}\right)$.


Figure 4.3. The shaded region represents $\widehat{f}_{i}^{-1}\left(E_{\text {thin }}\right)$.

Let $\mathcal{H}\left(\widehat{f}_{i}\right) \cap \widehat{f}_{i}^{-1}\left(E_{\text {thin }}\right)=\mathcal{H}\left(\widehat{f}_{i}\right)_{\text {tube }}$. We consider the unions of closed curves

$$
\begin{equation*}
\widehat{\mathcal{H}}_{i}=\widehat{f}_{i}\left(\mathcal{H}\left(\widehat{f}_{i}\right)\right) \quad \text { and } \quad \widehat{\mathcal{H}}_{i, \text { tube }}=\widehat{f}_{i}\left(\mathcal{H}\left(\widehat{f}_{i}\right)_{\text {tube }}\right) \tag{4.2}
\end{equation*}
$$

in $E$.

For simplicity, throughout the remainder of this section, we set $\widehat{f}_{i}\left(\widehat{\Sigma}_{i}\right)=\widehat{f_{i}}(\Sigma)$ and $\widehat{f}_{i}\left(\tau_{i}\right)=\left\{\widehat{f}_{i}(\sigma) ; \sigma \in \tau_{i}\right\}$. A singular 2-simplex $\sigma: \Delta^{2} \longrightarrow \widehat{f}_{i}(\Sigma)$ is called a 2-simplex with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i \text {, tube }}$ if, for any edge $e$ of $\Delta^{2}$, either $\sigma(e)$ is an element of $\widehat{f}_{i}\left(\tau_{i}^{(0)} \cup \tau_{i}^{(1)}\right)$ (possibly an ideal vertex) or the restriction $\left.\sigma\right|_{e}$ is an immersion into $\widehat{\mathcal{H}}_{i, \text { tube }}$ connecting two points of $\widehat{f}_{i}\left(\tau_{i}^{(0)}\right)$. In the latter case $\widehat{f}_{i}(e)$ is not necessarily contained in $\widehat{f}_{i}\left(\tau_{i}^{(0)} \cup \tau_{i}^{(1)}\right)$. In either case, $\left.\sigma\right|_{e}$ is called a 1-simplex with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i, \text { tube }}$. Since $\widehat{f}_{i}(\Sigma)$ is not necessarily a closed surface, any simplicial 2-cycle on $\widehat{f}_{i}(\Sigma)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i, \text { tube }}$ is supposed to represent a class of the locally finite homology group $H_{2}^{\text {loc.f. }}\left(\widehat{f}_{i}(\Sigma), \mathbb{R}\right)$.

The following lemma shows a sort of linear isoperimetric inequality for $\widehat{f_{i}}\left(\tau_{i}\right)$ $\bmod \widehat{\mathcal{H}}_{i, \text { tube }}$.

Lemma 4.1. There exists a uniform integer $L_{0}>0$ satisfying the following condition. Let $\widehat{c}=\widehat{e}_{1}+\widehat{e}_{2}+\cdots+\widehat{e}_{n}$ be any contractible 1-cycle on $\widehat{f}_{i}(\Sigma)$ such that each $\widehat{e}_{j}$ is a 1-simplex with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i \text {,tube }}$. Then $\widehat{c}$ bounds a simplicial 2-chain $\widehat{w}$ of disk type on $\widehat{f}_{i}(\Sigma)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i \text {,tube }}$ such that $\|\widehat{w}\| \leq L_{0}\|\widehat{c}\|$.
Proof. Let $D$ be an (abstract) 2-disk bounded by $\widehat{c}$ and let $g: D \longrightarrow \widehat{f}_{i}(\Sigma)$ be a continuous map extending $\widehat{c}$. If necessary deforming $g$ by homotopy rel. $\widehat{c}$, we may assume that $D$ has a simplicial decomposition $\widehat{\tau}$ such that, for each element $\Delta$ of $\widehat{\tau}$, the restriction $\left.g\right|_{\Delta}$ is a simplex on $\widehat{f}_{i}(\Sigma)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i, \text { tube }}$. Then $D$ is divided to sub-disks $D_{1}, \ldots, D_{k_{0}}, D_{1}^{\prime}, \ldots, D_{l_{0}}^{\prime}$ with $k_{0}, l_{0} \leq\|\widehat{c}\|=n$ and satisfying the following conditions.

- For each $k=1, \ldots, k_{0}, \operatorname{Int} D_{k}$ is a component of $\operatorname{Int} D \backslash g^{-1}\left(\widehat{\mathcal{H}}_{i}\right)$.
- For each $l=1, \ldots, l_{0}, D_{l}^{\prime}$ is the closure of a component of $D \backslash D_{1} \cup \cdots \cup D_{k_{0}}$. In the degenerate case, $D_{l}^{\prime}$ is an arc connecting two vertices of $\widehat{c}$.
See Figure 4.4. We may assume that, if $b^{\prime}=D_{k} \cap D_{l}^{\prime}$ is an arc connecting two vertices of $\widehat{c}$, then $\left.g\right|_{b^{\prime}}$ is an immersion. It is possible unless $g\left(b^{\prime}\right)$ is a single point. Otherwise, one can divide $\widehat{c}$ into two contractible 1-cycles $\widehat{c}_{1}$ and $\widehat{c}_{2}$ with $\left\|\widehat{c}_{1}\right\|+\left\|\widehat{c}_{2}\right\|=\|\widehat{c}\|$ by pinching $\widehat{c}$ along $\left.g\right|_{b^{\prime}}$, which reduces the proof to the case of contractible 1-cycles with smaller Gromov norm.

Let $\mathcal{D}=D_{1} \cup \cdots \cup D_{k_{0}}$ and $\mathcal{D}^{\prime}=D_{1}^{\prime} \cup \cdots \cup D_{l_{0}}^{\prime}$. Suppose that $D_{k}$ is a 'polygon' consisting of edges $b_{k, 1}, \ldots, b_{k, m_{k}}$ and arcs $b_{k, 1}^{\prime}, \ldots, b_{k, m_{k}}^{\prime}$ such that $g\left(\operatorname{Int} b_{k, u}\right) \subset$ $\widehat{f}_{i}(\Sigma) \backslash \widehat{\mathcal{H}}_{i}$ and $g\left(b_{k, u}^{\prime}\right) \subset \widehat{\mathcal{H}}_{i}$ for $u=1, \ldots, m_{k}$. Note that $b_{k, u}^{\prime}$ possibly consists of a single point. Set $\mathcal{B}_{k}^{\prime}=b_{k, 1}^{\prime} \cup \cdots \cup b_{k, m_{k}}^{\prime}$. Any element of $\left.\widehat{\tau}^{(1)}\right|_{D_{k}}$ not in $\mathcal{B}_{k}^{\prime}$ connects distinct components of $\mathcal{B}_{k}^{\prime}$. The number of such elements is at most $2 m_{k}-3$ up to proper homotopy on $\left(D_{k}, g^{-1}\left(\widehat{\mathcal{H}}_{i}\right) \cap D_{k}\right)$. By the property (T3) on $\tau_{i}$, any property homotopy class contains at most five elements of $\left.\widehat{\tau}^{(1)}\right|_{D_{k}}$. See Figure 4.5 for the case with maximal edges. Then we have $\#\left(\left.\left.\widehat{\tau}^{(1)}\right|_{D_{k}} \backslash \widehat{\tau}^{(1)}\right|_{\mathcal{B}_{k}^{\prime}}\right) \leq 5\left(2 m_{k}-3\right) \leq 10 m_{k}-15$ and hence $\#\left(\left.\widehat{\tau}^{(2)}\right|_{D_{k}}\right) \leq 10 m_{k}-14$. So the inequality $\#\left(\left.\widehat{\tau}^{(2)}\right|_{\mathcal{D}}\right) \leq \sum_{k=1}^{k_{0}}\left(10 m_{k}-\right.$ $14)<10 n$ holds. Since each vertex of $\left.\widehat{\tau}\right|_{D_{k}}$ not in $\partial D$ is end points of at least two elements of $\left.\left.\widehat{\tau}^{(1)}\right|_{D_{k}} \backslash \widehat{\tau}^{(1)}\right|_{\mathcal{B}_{k}^{\prime}}, \#\left(\left.\widehat{\tau}^{(0)}\right|_{\mathcal{D} \backslash \partial D}\right) \leq \sum_{k=1}^{k_{0}} 5\left(2 m_{k}-3\right)<10 n$. Since $\#\left(\left.\widehat{\tau}^{(0)}\right|_{\mathcal{D}^{\prime} \backslash \partial D}\right)=\#\left(\left.\widehat{\tau}^{(0)}\right|_{\mathcal{D} \backslash \partial D}\right)$, we have $\#\left(\left.\widehat{\tau}^{(0)}\right|_{\mathcal{D}^{\prime}}\right)<10 n+n=11 n$. It follows that $\#\left(\left.\widehat{\tau}^{(2)}\right|_{\mathcal{D}^{\prime}}\right)<11 n$. Thus $L_{0}=10+11=21$ is our desired uniform integer.


Figure 4.4. Simplicial decompositions of $D_{2}$ and $D_{3}^{\prime}$ with $m_{2}=7, \#\left(\left.\widehat{\tau}^{(0)}\right|_{\partial D_{2}}\right)=16$ and $\#\left(\left.\widehat{\tau}^{(0)}\right|_{\partial D_{3}^{\prime}}\right)=15$. Each square dot $p$ is a point contained in an element $e$ of $\left.\widehat{\tau}^{(1)}\right|_{D_{3}^{\prime}}$ with $\left.p \notin \widehat{\tau}^{(0)}\right|_{D_{3}^{\prime}}$ and $\left.g(p) \in \widehat{f}_{i}\left(\tau_{i}^{(0)}\right)\right|_{\widehat{\mathcal{H}}_{i, \text { tube }}}$.


Figure 4.5. The five blue segments in $D_{k}$ represent properly homotopic elements of $\left.\widehat{\tau}^{(1)}\right|_{D_{k}}$ whose $g$-images are distinct edges of $\widehat{f}_{i}\left(\tau_{i}\right)$.

## 5. Connection of smearing 3-CHAINS with normalized triangulations

Now we suppose that the constant $R$ given in Section 2 is at least 4 and prove the following connecting lemma, which plays an important role in the proof of Theorem A.

Lemma 5.1 (Connecting Lemma). Let $\sigma: \Delta^{3} \longrightarrow \mathbb{H}^{3}$ be a straight 3-simplex with $\operatorname{Vol}(\sigma)>1$ and $\widehat{X}=E\left(\widehat{f}_{0}, \widehat{f_{1}}\right)$. Then there exists a 3 -chain $z$ on $M$ satisfying the following conditions.
(1) $z=z_{\widehat{X}}(\sigma)+\widehat{a}$, where $\widehat{a}$ is a 3 -chain on $M$ with $\|\widehat{a}\| \leq b_{0}$ for some uniform constant $b_{0}>0$.
(2) For $i=0,1$, there exists a simplicial 2-cycle $w\left(\tau_{i}\right)$ on $\widehat{f}_{i}(\Sigma)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i, \text { tube }}$ representing the fundamental class of $\widehat{f}_{i}(\Sigma)$ and satisfying

$$
\partial_{3} z=\operatorname{Vol}(\sigma)\left(w\left(\tau_{1}\right)-w\left(\tau_{0}\right)\right)
$$

In the case when $\widehat{f}_{i}(\Sigma) \cap E_{\text {cusp }} \neq \emptyset$, we deform $\widehat{f}_{i}$ temporarily by replacing the (totally geodesic) parabolic cusps of $\widehat{f}_{i}(\Sigma)$ by cusps of constant Gaussian curvature $>-1$. The modified map is still denoted by $\widehat{f_{i}}$. Since $r \geq 4$, one can choose such cusps so that $\mathcal{N}_{4}\left(\widehat{f_{0}}(\Sigma)\right) \cap \mathcal{N}_{4}\left(\widehat{f_{1}}(\Sigma)\right)=\emptyset$. See Figure 5.1. For $i=0,1$, let $\mathcal{L}_{4, i}$


Figure 5.1
be the closure of the component of $\mathcal{N}_{4}\left(\widehat{f}_{i}(\Sigma)\right) \backslash \widehat{f_{i}}(\Sigma)$ contained in $\widehat{X}$ and let $\widehat{Y}$ be the closure of $\widehat{X} \backslash\left(\mathcal{L}_{4,0} \sqcup \mathcal{L}_{4,1}\right)$. The intersection $F_{i}=\mathcal{L}_{4, i} \cap \widehat{Y}$ is the union of components of $\partial \mathcal{L}_{4, i}$ adjacent to $\widehat{Y}$.

Let $w_{k}(k=2,3)$ be any $k$-chain with $\operatorname{supp}\left(w_{3}\right) \subset \operatorname{supp}\left(z_{M}(\sigma)\right)$ and $\operatorname{supp}\left(w_{2}\right) \subset$ $\operatorname{supp}^{(2)}\left(z_{M}(\sigma)\right)$. See (3.5) for the definition of $\operatorname{supp}^{(2)}(\cdot)$. We denote by $w_{3}\left(\xi_{0}\right)$ the 3 -chain obtained by replacing each 3 -simplex $\sigma^{\prime}$ of $\operatorname{supp}\left(w_{3}\right)$ with the sum $\left.\sum_{D \in \tau\left(\sigma, \xi_{0}\right)^{(3)}} \sigma^{\prime}\right|_{D}$. The subdivision $w_{2}\left(\xi_{0}\right)$ of $w_{2}$ is defined similarly. By (4.1), $\left(\partial_{3} w_{3}\right)\left(\xi_{0}\right)=\partial_{3}\left(w_{3}\left(\xi_{0}\right)\right)$. So one can denote it as $\partial_{3} w_{3}\left(\xi_{0}\right)$. For any closed subset $A$ of $M$, we denote by $\left.w_{k}\right|_{A}$ the sub-chain of $w_{k}$ consisting of $\sigma^{\prime} \in \operatorname{supp}\left(w_{k}\right)$ whose inner center $o\left(\sigma^{\prime}\right)$ is contained in $A$. In particular, $\left.z_{M}(\sigma)\right|_{A}=z_{A}(\sigma)$. We denote $\left.\left(\partial_{3} w_{3}\right)\right|_{A}$ by $\left.\partial_{3} w_{3}\right|_{A}$ shortly.

Proof of Lemma 5.1. The proof is done in five steps. Figure 5.2 illustrates our process schematically, where $w_{1} \xrightarrow{z} w_{2}$ means that $\partial_{3} z=w_{2}-w_{1}$.
Step 1. For $i=0,1$, we set $u_{i}\left(\xi_{0}\right)=z_{\mathcal{N}_{2}\left(\widehat{f_{i}}(\Sigma)\right) \cup \mathcal{L}_{4, i}}(\sigma)\left(\xi_{0}\right)$. Let $\sigma^{\prime \prime}$ be any element of $\operatorname{supp}\left(z_{M}(\sigma)\left(\xi_{0}\right)\right)$ with $o\left(\sigma^{\prime \prime}\right) \in \mathcal{N}_{2}\left(\widehat{f}_{i}(\Sigma)\right) \cap \mathcal{L}_{4, i}$. See Figure 5.3, where the center region represents $\mathcal{N}_{2}\left(\widehat{f}_{1}(\Sigma)\right) \cap \mathcal{L}_{4,1}$. Note that $\sigma^{\prime \prime}$ is represented as $\left.\sigma^{\prime}\right|_{D}$ for some $\sigma^{\prime} \in \operatorname{supp}\left(z_{M}(\sigma)\right)$ and $D \in \tau\left(\sigma, \xi_{0}\right)^{(3)}$. From the definition of $\tau\left(\Delta, \xi_{0}\right)$ together with elementary hyperbolic geometry, one can prove that $\operatorname{dist}_{M}\left(o\left(\sigma^{\prime \prime}\right), o\left(\sigma^{\prime}\right)\right)<2$. Here ' 2 ' is not essential. We just need a positive uniform constant. Then $o\left(\sigma^{\prime}\right)$ is contained in $\mathcal{N}_{2}\left(\widehat{f}_{i}(\Sigma)\right) \cup \mathcal{L}_{4, i}$ and hence $\sigma^{\prime \prime} \in \operatorname{supp}\left(\left.u_{i}\left(\xi_{0}\right)\right|_{\widehat{X}}\right)$. Note that the point $o\left(\sigma^{\prime}\right)$ is not necessarily an element of $\mathcal{L}_{4, i}$, which is the reason why we use


Figure 5.2. The union of blue segments represents $z_{\xi_{0}}$, that of blues and reds does $\widehat{z}_{\xi_{0}}$, and that of greens does $\widehat{a}$.
$z_{\mathcal{N}_{2}\left(\widehat{f}_{i}(\Sigma)\right) \cup \mathcal{L}_{4, i}}(\sigma)\left(\xi_{0}\right)$ but not $z_{\mathcal{L}_{4, i}}(\sigma)\left(\xi_{0}\right)$ to define $u_{i}\left(\xi_{0}\right)$. See Figure 5.3. By Lemma 3.1,

$$
\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\left(\xi_{0}\right)=\left(\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)\left(\xi_{0}\right)+\left(\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(\widehat{f_{i}}(\Sigma)\right)}\right)\left(\xi_{0}\right)
$$

Strictly, for any 3 -chain $w$ on $M$ and any subset $A$ of $M,\left.\partial_{3} w\right|_{A}$ means $\left.\left(\partial_{3} w\right)\right|_{A}$.


Figure 5.3. The case of $o\left(\sigma^{\prime}\right) \in \mathcal{N}_{2}\left(\widehat{f_{1}}(\Sigma)\right) \backslash \mathcal{L}_{4,1}$.

In general, $\left.\left(\partial_{3} w\right)\right|_{A}$ is not equal to $\partial_{3}\left(\left.w\right|_{A}\right)$. Take a small $\varepsilon>0$ arbitrarily. Since $\operatorname{Int} \mathcal{N}_{2}\left(\widehat{f}_{i}(\Sigma)\right) \cap \mathcal{N}_{2}\left(F_{i}\right)=\emptyset, \partial_{3}\left(\left.u_{i}\left(\xi_{0}\right)\right|_{\widehat{X}}\right)$ is represented as the sum

$$
\partial_{3}\left(\left.u_{i}\left(\xi_{0}\right)\right|_{\widehat{X}}\right)=\left(\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)\left(\xi_{0}\right)+t_{i}\left(\xi_{0}\right)
$$

such that $t_{i}\left(\xi_{0}\right)$ is the sub-chain of $\partial_{3}\left(\left.u_{i}\left(\xi_{0}\right)\right|_{\hat{X}}\right)$ consisting of 2-simplices $\sigma^{\prime \prime} \in$ $\operatorname{supp}\left(\partial_{3}\left(\left.u_{i}\left(\xi_{0}\right)\right|_{\widehat{X}}\right)\right)$ with $o\left(\sigma^{\prime \prime}\right) \in \operatorname{Int} \mathcal{N}_{2}\left(\widehat{f}_{i}(\Sigma)\right)$ or equivalently $o\left(\sigma^{\prime \prime}\right) \in \mathcal{N}_{\varepsilon}\left(\widehat{f}_{i}(\Sigma)\right)$ if $\xi_{0}=\xi_{0}(\varepsilon)>0$ is taken sufficiently small. See Figure 5.2.

Step 2. Since $\mathcal{N}_{2}\left(F_{i}\right) \cap \operatorname{Int} \mathcal{N}_{2}(\partial \widehat{X})$ is empty,

$$
\operatorname{supp}\left(\left.\partial_{3} z_{\mathcal{L}_{4, i} U \widehat{Y}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)=\operatorname{supp}\left(\left.\partial_{3} z_{\widehat{X}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)=\emptyset
$$

So, we have $\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}=-\left.\partial_{3} z_{\widehat{\mathcal{Y}}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}$. Here we consider a chain homotopy $z_{F_{i}}$ between $\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}$ and its subdivision $\left(\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)\left(\xi_{0}\right)$. Since $\mathcal{N}_{2}\left(F_{i}\right) \subset \mathcal{N}_{6}\left(\widehat{f_{i}}(\Sigma)\right)$, there exists a 3 -chain $z_{F_{i}}$ consisting of 3-simplices whose inner centers are contained in $\mathcal{N}_{2}\left(F_{i}\right)$ and satisfying

$$
\begin{aligned}
\partial_{3} z_{F_{i}} & =-\left(\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)\left(\xi_{0}\right)+\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)} \\
& =-\left(\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right)\left(\xi_{0}\right)-\left.\partial_{3} z_{\widehat{Y}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}
\end{aligned}
$$

and

$$
\begin{align*}
\left\|z_{F_{i}}\right\| & \leq 3\left\|\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\left(\xi_{0}\right)\right\| \leq 3 n_{0}\left(\xi_{0}\right)\left\|\left.\partial_{3} z_{\mathcal{L}_{4, i}}(\sigma)\right|_{\mathcal{N}_{2}\left(F_{i}\right)}\right\| \\
& =3 n_{0}\left(\xi_{0}\right) \operatorname{Vol}\left(\mathcal{N}_{2}\left(F_{i}\right)\right) \leq 3 n_{0}\left(\xi_{0}\right) v_{0}(6) \tag{5.1}
\end{align*}
$$

where $n_{0}\left(\xi_{0}\right)$ is the cardinality of $\tau\left(\Delta, \xi_{0}\right)^{(3)}, v_{0}(6)$ is the constant given in Lemma 2.1 (3) and ' 3 ' means that the triangular prism $\Delta^{2} \times[0,1]$ is divided into three 3 -simplices. Consider the 3 -chain

$$
\begin{equation*}
z_{\xi_{0}}=\left.u_{0}\left(\xi_{0}\right)\right|_{\widehat{X}}-z_{F_{0}}+z_{\widehat{Y}}(\sigma)+z_{F_{1}}+\left.u_{1}\left(\xi_{0}\right)\right|_{\widehat{X}} \tag{5.2}
\end{equation*}
$$

See Figure 5.2 again. Since $z_{\xi_{0}}$ consists of 3 -simplices whose inner centers are contained $\mathcal{N}_{\varepsilon}(\widehat{X})$,

$$
\operatorname{supp}\left(\partial_{3} z_{\xi_{0}}\right) \subset \operatorname{supp}^{(2)}\left(\left.z_{\xi_{0}}\right|_{\mathcal{N}_{\varepsilon}\left(\widehat{f_{0}}(\Sigma)\right) \sqcup \mathcal{N}_{\varepsilon}\left(\widehat{f_{1}}(\Sigma)\right)}\right) .
$$

By (5.1),

$$
\begin{align*}
\left\|z_{\xi_{0}}-z_{\widehat{Y}}(\sigma)\right\| & =\left\|\left.u_{0}\left(\xi_{0}\right)\right|_{\widehat{X}}\right\|+\left\|z_{F_{0}}\right\|+\left\|z_{F_{1}}\right\|+\left\|\left.u_{1}\left(\xi_{0}\right)\right|_{\widehat{X}}\right\| \\
& \leq 2 n_{0}\left(\xi_{0}\right) v_{0}(2)+6 n_{0}\left(\xi_{0}\right) v_{0}(6)  \tag{5.3}\\
& =2 n_{0}\left(\xi_{0}\right)\left(v_{0}(2)+3 v_{0}(6)\right)
\end{align*}
$$

In the following two steps, we will define 3-chains $\widehat{z}_{0}$ and $\widehat{z}_{1}$ with $\partial_{3} \widehat{z}_{i}=v w\left(\tau_{i}\right)-$ $t_{i}\left(\xi_{0}\right)(i=0,1)$ for some constant $v>0$, which is shown to equal $\operatorname{Vol}(\sigma)$ in Step 5.
Step 3. By $(5.2),\left.\partial_{3} z_{\xi_{0}}\right|_{\mathcal{N}_{\varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)}=\left.\partial_{3}\left(\left.u_{i}\left(\xi_{0}\right)\right|_{\widehat{X}}\right)\right|_{\mathcal{N}_{\varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)}$. Let $w_{i, \text { inn }}$, $w_{i, \text { out }}$ be the 2 -sub-chains of $\left.\partial_{3} z_{\xi_{0}}\right|_{\mathcal{N}_{\varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)}$ corresponding to elements of $\tau\left(\Delta, \xi_{0}\right)_{\text {inn }}^{(2)}$ and $\tau\left(\Delta, \xi_{0}\right)_{\text {out }}^{(2)}$ respectively. Since $\partial_{2}\left(\left.\partial_{3} z \xi_{0}\right|_{\mathcal{N}_{\varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)}\right)=0, \partial_{2} w_{i, \text { inn }}=-\partial_{2} w_{i, \text { out }}$. By the geometrical boundedness of normalized maps in thick parts, we may assume that there exists a projection $\operatorname{pr}_{i}: \mathcal{N}_{2 \varepsilon}\left(\widehat{f}_{i}(\Sigma)\right) \longrightarrow \widehat{f}_{i}(\Sigma)$ which is 2-Lipschitz on $\mathcal{N}_{2 \varepsilon}\left(\widehat{f}_{i}(\Sigma)\right) \cap E_{\text {thick }}$ and with $\operatorname{pr}_{i}\left(\mathcal{N}_{2 \varepsilon}\left(\widehat{f}_{i}(\Sigma)\right) \cap E_{\text {thin }}\right) \subset \widehat{f}_{i}(\Sigma) \cap E_{\text {thin }}$ if necessary replacing $\varepsilon$ by a smaller positive number, where ' 2 ' is taken as a constant greater than 1. Here one can retake $\xi_{0}>0$ if necessary so that $\operatorname{diam}\left(\sigma^{\prime}\left(\Delta^{2}\right)\right)<\varepsilon$ for any 2-simplex $\sigma^{\prime}$ in $w_{i \text { inn }}$. Since $o\left(\sigma^{\prime}\right) \in \mathcal{N}_{\varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)$, it follows that $\sigma^{\prime}\left(\Delta^{2}\right)$ is contained in $\mathcal{N}_{2 \varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)$. Then there exists a 3 -chain $z_{i, \text { inn }}$ on $\mathcal{N}_{2 \varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)$ with

$$
\begin{equation*}
\partial_{3} z_{i, \mathrm{inn}}=\operatorname{pr}_{i *}\left(w_{i, \mathrm{inn}}\right)+p_{i}-w_{i, \mathrm{inn}} \tag{5.4}
\end{equation*}
$$

where $p_{i}$ is the product simplicial complex isomorphic to $\partial_{2} w_{i, \text { inn }} \times[0,1]$ and with $\partial_{2} p_{i}=\partial_{2} w_{i, \text { inn }}-\partial_{2}\left(\operatorname{pr}_{i *}\left(w_{i, \text { inn }}\right)\right)$. By Lemma $2.1(3)$,

$$
\begin{align*}
\left\|p_{i}\right\| & \leq 2\left\|\partial_{2} w_{i, \mathrm{inn}}\right\| \leq 2 \cdot 3\left\|w_{i, \mathrm{inn}}\right\| \leq 2 \cdot 3 \cdot 4\left\|\left.z_{\xi_{0}}\right|_{\mathcal{N}_{2 \varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)}\right\|  \tag{5.5}\\
& \leq 24 n_{0}\left(\xi_{0}\right) \operatorname{Vol}\left(\mathcal{N}_{2}\left(\widehat{f}_{i}(\Sigma)\right)\right) \leq 24 n_{0}\left(\xi_{0}\right) v_{0}(2)
\end{align*}
$$

where ' 2 ' means that any rectangle is divided into two 2 -simplices, ' 3 ' any 2 -simplex has three edges, and ' 4 ' any 3 -simplex has four 2 -faces. We retake $\xi_{0}>0$ sufficiently small if necessary so that the diameter of $\operatorname{pr}_{i}\left(\sigma^{\prime}\left(\Delta^{2}\right)\right) \cap E_{\text {thick }}$ for any 2-simplex $\sigma^{\prime}$ in $w_{i, \text { inn }}$ is less than the constant $d_{1}$ given in (T5). By (5.4) together with a standard argument of simplicial approximation of homology theory (for example see Spanier [Sp, Section 3.4]), we know that there exists a simplicial 2-chain $\widehat{w}_{i, \text { inn }}$ on $\widehat{f}_{i}(\Sigma)$ and a simplicial 3-chain $\widehat{z}_{i, \text { inn }}$ on $\mathcal{N}_{2 \varepsilon}\left(\widehat{f_{i}}(\Sigma)\right)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right)$ mod $\widehat{\mathcal{H}}_{i \text {,tube }}$ such that $\partial_{3} \widehat{z}_{i, \text { inn }}=\widehat{w}_{i, \text { inn }}+\widehat{p}_{i}-w_{i, \text { inn }}$, where $\widehat{p}_{i}$ is the product simplicial complex isomorphic to $p_{i}$ with $\partial_{2} \widehat{p}_{i}=\partial_{2} w_{i, \text { inn }}-\partial_{2} \widehat{w}_{i, \text { inn }}$. See Figure $5.4(\mathrm{a})$. Since any triangular prism


Figure 5.4
is divided into three 3 -simplices, one can choose the 3 -chain $\widehat{z}_{i \text { inn }}$ so that

$$
\begin{equation*}
\left\|\widehat{z}_{i, \text { inn }}\right\| \leq 3\left\|w_{i, \text { inn }}\right\| \leq 12 n_{0}\left(\xi_{0}\right) v_{0}(2) \tag{5.6}
\end{equation*}
$$

holds. See Figure 5.5.
Step 4. If necessary replacing $w_{i, \text { out }}$ by a usual locally finite singular 2-chain as in Remark 3.2, we may assume that $\partial_{2} w_{i \text {,out }}$ is a locally finite sum of 1-cycles $c_{i \alpha}$. Suppose that $c_{i \alpha}$ is represented as $e_{1}+\cdots+e_{n}$ for $e_{1}, \ldots, e_{n} \in W_{i, \text { out }}^{(1)}$, where $W_{i, \text { out }}$ is the minimum simplicial complex containing the terms of $w_{i, \text { out }}$. From the construction of $w_{i, \text { out }}$, there exist isosceles hyperbolic 2-simplices $\Delta_{1}, \ldots, \Delta_{n} \in$ $W_{i, \text { out }}^{(2)}$ which have a common vertex $v_{0}$ and such that the sum $\Delta\left(c_{i \alpha}\right)=\Delta_{1}+\cdots+\Delta_{n}$ is a 2-chain satisfying $\partial_{2} \Delta\left(c_{i \alpha}\right)=c_{i \alpha}$. See Figure $5.4(\mathrm{~b})$. Thus $c_{i \alpha}$ is a 1-cycle in $\partial_{2} w_{i, \text { inn }}=-\partial_{2} w_{i, \text { out }}$ contractible in $E$. Since $\widehat{f}_{i}(\Sigma)$ is incompressible in $E, \partial_{2} \widehat{w}_{i, \text { inn }}$ is also a locally finite sum of 1-cycles $\widehat{c}_{i \alpha}$ contractible in $\widehat{f}_{i}(\Sigma)$. By Lemma 4.1, $\widehat{c}_{i \alpha}$ bounds a simplicial 2-chain $\widehat{w}\left(c_{i \alpha}\right)$ of disk type in $\widehat{f}_{i}(\Sigma)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right)$ $\bmod \widehat{\mathcal{H}}_{i, \text { tube }}$ such that $\left\|\widehat{w}\left(c_{i \alpha}\right)\right\| \leq L_{0}\left\|\widehat{c}_{i \alpha}\right\| \leq L_{0}\left\|c_{i \alpha}\right\|$. Let $\widehat{w}_{i, \text { out }}$ be the sum of all


Figure 5.5. The gray region represents $\mathcal{N}_{2 \varepsilon}\left(\widehat{f}_{1}(\Sigma)\right)$. Each white dot represents a 1-cycle either in $\partial_{2} w_{1, \text { inn }}=-\partial_{2} w_{1, \text { out }}$ or in $\partial_{2} \widehat{w}_{1, \text { inn }}=-\partial_{2} \widehat{w}_{1, \text { out }}$.
$\widehat{w}\left(c_{i, \alpha}\right)$ 's. Then, as (5.5),

$$
\begin{aligned}
\left\|\widehat{w}_{i, \text { out }}\right\| & \leq L_{0} \sum_{\alpha}\left\|c_{i \alpha}\right\| \leq L_{0}\left\|c_{i \alpha}\right\|=L_{0}\left\|\partial_{2} w_{i, \text { out }}\right\|=L_{0}\left\|\partial_{2} w_{i, \text { inn }}\right\| \\
& \leq 4 L_{0} n_{0}\left(\xi_{0}\right) v_{0}(2)
\end{aligned}
$$

Thus $\widehat{w}_{i}=\widehat{w}_{i, \text { inn }}+\widehat{w}_{i, \text { out }}$ is a locally finite simplicial 2-cycle on $\widehat{f}_{i}(\Sigma)$ with respect to $\widehat{f}_{i}\left(\tau_{i}\right) \bmod \widehat{\mathcal{H}}_{i, \text { tube }}$ with $\left\|\widehat{w}_{i}\right\| \leq 4\left(L_{0}+1\right) n_{0}\left(\xi_{0}\right) v_{0}(2)$.

Consider the 3 -chain $\theta\left(c_{i \alpha}\right)$ obtained by suspending the 2 -sphere cycle $\Delta\left(c_{i \alpha}\right)-$ $\widehat{p}\left(c_{i \alpha}\right)+\widehat{w}\left(c_{i \alpha}\right)$ with a vertex $o\left(c_{i \alpha}\right)$. See Figure 5.5 again. Then we have $\partial_{3} \theta\left(c_{i \alpha}\right)=$ $\Delta\left(c_{i \alpha}\right)+\widehat{p}\left(c_{i \alpha}\right)-\widehat{w}\left(c_{i \alpha}\right)$ and $\left\|\theta\left(c_{i \alpha}\right)\right\| \leq\left(L_{0}+3\right)\left\|c_{i \alpha}\right\|$. Here ' $3(=2+1)^{\prime}$ means that $\left\|\widehat{p}\left(c_{i \alpha}\right)\right\| \leq 2\left\|c_{i \alpha}\right\|$ and $\left\|\delta\left(c_{i \alpha}\right)\right\| \leq\left\|c_{i \alpha}\right\|$. Let $\widehat{z}_{i, \text { out }}$ be the sum of all $\theta\left(c_{i \alpha}\right)$ 's. Then

$$
\begin{equation*}
\left\|\widehat{z}_{i, \text { out }}\right\| \leq \sum_{\alpha}\left(L_{0}+3\right)\left\|c_{i \alpha}\right\| \leq 4\left(L_{0}+3\right) n_{0}\left(\xi_{0}\right) v_{0}(2) \tag{5.7}
\end{equation*}
$$

We set $\widehat{z}_{i}=\widehat{z}_{i, \text { inn }}+\widehat{z}_{i, \text { out }}$. By (5.6) and (5.7),

$$
\begin{equation*}
\left\|\widehat{z}_{i}\right\| \leq 12 n_{0}\left(\xi_{0}\right) v_{0}(2)+4\left(L_{0}+3\right) n_{0}\left(\xi_{0}\right) v_{0}(2) \leq 4\left(L_{0}+6\right) n_{0}\left(\xi_{0}\right) v_{0}(2) \tag{5.8}
\end{equation*}
$$

In the last step, we will construct a 3 -chain $z$ satisfying the conditions (1) and (2) of this lemma.

Step 5. Let $\widehat{z}_{x i_{0}}$ be the 3 -chain defined by $\widehat{z}_{\xi_{0}}=-\widehat{z}_{0}+z_{\xi_{0}}+\widehat{z}_{1}$. See Figure 5.2. It follows from the definition that

$$
\partial_{3} \widehat{z}_{\xi_{0}}=\widehat{w}_{1}-\widehat{w}_{0} .
$$

Consider the 3-chain $\widehat{a}$ defined by $\widehat{a}=\widehat{z}_{\xi_{0}}-z_{\widehat{X}}(\sigma)=\widehat{z}_{0}+z_{\xi_{0}}+\widehat{z}_{1}-z_{\widehat{X}}(\sigma)$. See
Figure 5.2. Since $\widehat{X} \backslash \widehat{Y} \subset \mathcal{N}_{2}\left(\widehat{f_{0}}(\Sigma)\right) \cup \mathcal{N}_{2}\left(\widehat{f_{1}}(\Sigma)\right)$, by (5.3) and (5.8)

$$
\begin{aligned}
\|\widehat{a}\| & \leq\left\|z_{\widehat{X} \backslash \widehat{Y}}(\sigma)\right\|+\left\|\widehat{z}_{0}\right\|+\left\|z_{\xi_{0}}-z_{\widehat{Y}}(\sigma)\right\|+\left\|\widehat{z}_{1}\right\| \\
& \leq \operatorname{Vol}(\widehat{X} \backslash \widehat{Y})+8\left(L_{0}+6\right) n_{0}\left(\xi_{0}\right) v_{0}(2)+2 n_{0}\left(\xi_{0}\right)\left(v_{0}(2)+3 v_{0}(6)\right) \\
& <2 v_{0}(2)+\left(8\left(L_{0}+6\right)+2\right) n_{0}\left(\xi_{0}\right) v_{0}(2)+6 n_{0}\left(\xi_{0}\right) v_{0}(6)=: b_{0} .
\end{aligned}
$$

In the case of $\widehat{f}_{i}(\Sigma) \cap E_{\text {cusp }} \neq \emptyset$, we deform $z$ by a projection in $E_{\text {cusp }}$ sending $\widehat{f_{i}}(\Sigma) \cap E_{\text {cusp }}$ to the totally geodesic cusps in $E_{\text {cusp }}$ without moving $\widehat{f_{i}}(\Sigma) \cap \partial E_{\text {cusp }}$. See the $E_{\text {cusp }}$-part in Figure 5.1. The deformation is accomplished by a chain homotopy consisting of 3 -simplices each of which has a 2 -face belonging to $\widehat{f_{0}}\left(\tau_{0}^{(2)}\right) \cup$ $\widehat{f_{1}}\left(\tau_{1}^{(2)}\right)$. This shows (1).

Note that

$$
z_{M}(\sigma)=\left(z_{\widehat{X}}(\sigma)+\widehat{a}\right)+\left(z_{M \backslash \operatorname{Int} \widehat{X}}(\sigma)-\widehat{a}\right)=\widehat{z}_{\xi_{0}}+\left(z_{M \backslash \operatorname{Int} \widehat{X}}(\sigma)-\widehat{a}\right)
$$

See Figure 5.6. By our construction of $\widehat{z}_{\xi_{0}}$, the boundary $\partial_{3} \widehat{z}_{\xi_{0}}$ has the form


Figure 5.6. The union of blue segments represents $z_{\widehat{X}}(\sigma)+\widehat{a}=\widehat{z}_{\xi_{0}}$ and that of reds does $z_{M \backslash \operatorname{Int} \widehat{X}}(\sigma)-\widehat{a}$.
$v\left(w\left(\tau_{1}\right)-w\left(\tau_{0}\right)\right)$ for some $v>0$. From the definition (3.4) of $z_{M}(\sigma)$ and (3.3), $z_{M}(\sigma)$ represents the class $\operatorname{Vol}(\sigma)[M]$ of the locally finite homology group $H_{3}^{\text {loc.f. }}(M, \mathbb{R})$. It follows that $v=\operatorname{Vol}(\sigma)$. Thus $z=\widehat{z}_{\xi_{0}}$ satisfies the condition (2) and hence it is our desired 3 -chain. This completes the proof of Lemma 5.1.

## 6. Proofs of Theorems A and C

First we recall the necessary conditions in Theorem A. Suppose that $M, M^{\prime}$ are oriented hyperbolic 3-manifolds with markings $\iota: \Sigma \longrightarrow M$ and $\iota^{\prime}: \Sigma \longrightarrow M^{\prime}$ which satisfy

$$
\begin{equation*}
\left\|\iota^{*}\left(\left[\omega_{M}\right]\right)-\iota^{\prime *}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|<\boldsymbol{v}_{3} \tag{0.1}
\end{equation*}
$$

in $H_{b}^{3}(\Sigma, \mathbb{R})$. Since both $M$ and $M^{\prime}$ are homeomorphic to $\Sigma \times \mathbb{R}$, there exists an orientation preserving homeomorphism $\varphi: M \longrightarrow M^{\prime}$ such that $\varphi \circ \iota$ is properly homotopic to $\iota^{\prime}$. So (0.1) is rewritten as

$$
\begin{equation*}
\left\|\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|<\boldsymbol{v}_{3} \tag{0.2}
\end{equation*}
$$

in $H_{b}^{3}(M, \mathbb{R})$. Here we consider the case that $(+)$-end $\mathcal{E}$ of $M$ is totally degenerate.
Let $E$ be the neighborhood of $\mathcal{E}$ with respect to $\iota(\Sigma)$ and set $E^{\prime}=\varphi(E)$.

For any piecewise smooth proper homotopy equivalences $f_{i}: \Sigma \longrightarrow M(i=0,1)$, there exists a piecewise smooth proper continuous map $Z: \Sigma \times[0,1] \longrightarrow E$ with $f_{0}=\left.Z\right|_{\Sigma \times\{0\}}$ and $f_{1}=\left.Z\right|_{\bar{\Sigma} \times\{1\}}$. Here $\bar{\Sigma}$ is equal to $\Sigma$ as a surface but it has the orientation opposite to that on $\Sigma$. Then the bounding volume $\operatorname{Vol}^{\text {bd }}(Z)$ of $Z$ is defined by

$$
\operatorname{Vol}^{\mathrm{bd}}(Z)=\int_{\Sigma \times[0,1]} Z^{*}\left(\Omega_{E}\right)
$$

where $\Omega_{E}$ is the volume form on $E$. It is a standard fact in homology theory that $\operatorname{Vol}^{\mathrm{bd}}(Z)$ is independent of the choice of the extension $Z$ of $f_{1}$ and $f_{2}$. Thus one can set $\operatorname{Vol}^{\text {bd }}(Z)=\operatorname{Vol}^{\text {bd }}\left(f_{0}, f_{1}\right)$. From the definition, $\operatorname{Vol}^{\text {bd }}\left(f_{1}, f_{0}\right)=-\operatorname{Vol}^{\text {bd }}\left(f_{0}, f_{1}\right)$ holds.

Now we are ready to prove Theorem A.
Proof of Theorem A. Recall that $M_{\text {(cusp) }}$ is the union of components of $M_{\text {cusp }}$ meeting $\iota\left(\Sigma_{\text {cusp }}\right)$ non-trivially. We denote by $E_{\text {cusp* }}$ the union of components $V$ of $E_{\text {cusp }}$ such that $\varphi(V)$ is freely homotopic into $E_{\text {cusp }}^{\prime}$ in $E^{\prime}$. In particular, $E_{\text {(cusp) }}$ is a subunion of $E_{\text {cusp* }}$. One can retake the homeomorphism $\varphi$ so that $E_{\text {cusp* }}^{\prime}=\varphi\left(E_{\text {cusp* }}\right)$ is a union of components of $E_{\text {cusp }}^{\prime}$. Let $C_{*}$ be a finite core of $M$ which meets each component of $E_{\text {cusp* }}$ non-trivially and is disjoint from $E_{\text {cusp }} \backslash E_{\text {cusp* }}$.

For any sub-end $\mathcal{E}^{b}$ of $\mathcal{E}$ with respect to $C_{*}$, let $E^{b}$ be the closure of the component of $E \backslash C_{*}$ adjacent to $\mathcal{E}^{b}$. Since $\mathcal{E}$ is totally degenerate, so is $\mathcal{E}^{b}$. Consider a sequence $\left\{\widehat{f}_{n}\right\}_{n=0}^{\infty}$ of normalized maps $\widehat{f}_{n}: \widehat{\Sigma}_{n}^{b} \longrightarrow E^{b}$ satisfying the conditions given in Section 2, where any $\widehat{\Sigma}_{n}^{b}$ admits a marking $\iota_{n}: \Sigma^{b} \longrightarrow \widehat{\Sigma}_{n}^{b}$ for a fixed complete hyperbolic surface $\Sigma^{b}$ of finite area. Note that $\Sigma^{b}$ is not homeomorphic to $\Sigma$ when $E_{\text {cusp* }} \neq E_{\text {(cusp) }}$ or equivalently the $(+)$-end $\mathcal{E}$ is not genuine. Let $\mathcal{H}\left(\widehat{f}_{n}\right)$ be a hoop family of $\widehat{\Sigma}_{n}^{b}$, see (4.2). Suppose that $\tau_{n}$ is a triangulation on $\Sigma^{b}$ such that $\widehat{\tau}_{n}=\iota_{n}\left(\tau_{n}\right)$ is a normalized triangulation with respect to $\mathcal{H}\left(\widehat{f}_{n}\right)$, which satisfies the conditions (T1)-(T5) given in Section 4. We consider the union $\widehat{\mathcal{H}}_{E^{b}}=\bigcup_{n=0}^{\infty} \widehat{\mathcal{H}}_{n}$ of $\widehat{\mathcal{H}}_{n}=\widehat{f}_{n}\left(\mathcal{H}\left(\widehat{f}_{n}\right)\right)$. Let $\mathcal{N}\left(\widehat{\mathcal{H}}_{E^{b}}\right)$ be a tubular neighborhood of $\widehat{\mathcal{H}}_{E^{b}}$ in $M$ consisting of mutually disjoint tubular neighborhoods with $\operatorname{Vol}\left(\mathcal{N}\left(\widehat{\mathcal{H}}_{E^{b}}\right)\right)=\sum_{n=0}^{\infty} \mathcal{N}\left(\widehat{\mathcal{H}}_{n}\right)<\infty$. Note that the normal radius of any components of $\mathcal{N}\left(\widehat{\mathcal{H}}_{n}\right)$ converges to zero as $n \rightarrow \infty$. From the definition of $C_{*}$, we know that any accidental cusp of $\mathcal{E}^{b}$ does not correspond to any cusp of $M^{\prime}$ via $\varphi$. So, if necessary removing finitely many entries from $\left\{\widehat{f}_{n}\right\}$, one can suppose that, for each component $l$ of $\widehat{\mathcal{H}}_{E^{b}}, \varphi(l)$ is not freely homotopic into $M_{\text {cusp }}^{\prime}$. Thus we have a continuous map $\psi: M \longrightarrow M^{\prime}$ satisfying the following conditions.
(P1) $\left.\psi\right|_{M \backslash \mathcal{N}\left(\widehat{\mathcal{H}}_{E^{b}}\right)}=\left.\varphi\right|_{M \backslash \mathcal{N}\left(\widehat{\mathcal{H}}_{E^{b}}\right)}$.
(P2) For each component $l$ of $\widehat{\mathcal{H}}_{E^{b}}, \psi(l)$ is a closed geodesic in $M^{\prime}$.
Consider a piecewise totally geodesic map $f_{n}^{\prime *}: \Sigma_{n}^{* *} \longrightarrow M^{\prime}$ properly homotopic to $\psi \circ \widehat{f}_{n}: \widehat{\Sigma}_{n}^{b} \longrightarrow M^{\prime}$ and satisfying the following conditions.

- For any $v \in \tau_{n}^{(0)}, f_{n}^{\prime *}(v)=\psi \circ \widehat{f}_{n}(v)$.
- For any $e \in \tau_{n}^{(1)}, f_{n}^{\prime \prime}(e)$ is a geodesic segment in $E^{\prime}$ homotopic to $\psi \circ \widehat{f}_{n}(e)$ rel. $\partial e$.
- For any $\Delta \in \tau_{n}^{(2)}, f_{n}^{\prime *}(\Delta)$ is a totally geodesic triangle in $E^{\prime}$ bounded by $f_{n}^{\prime *}(\partial \Delta)$.

Now we need to consider the following two cases.

Case 1. $\mathcal{E}^{b}$ has no accidental cusps.
Let $\sigma: \Delta^{3} \longrightarrow \mathbb{H}^{3}$ be any straight simplex in $\mathbb{H}^{3}$ with $\operatorname{Vol}(\sigma)>1$. For any $n \in \mathbb{N}$, suppose that $\widehat{a}_{0, n}$ is the connecting 3 -chain given in Lemma 5.1 (1) associated with $\widehat{X}=E^{b}\left(\widehat{f}_{0}, \widehat{f}_{n}\right)$ such that $\left\|\widehat{a}_{0, n}\right\|$ is less than a constant $b_{0}>0$ independent of $n$. Moreover, for the 3-chain $z_{0, n}=z(0, n)+\widehat{a}_{0, n}$ on $E, \partial_{3} z_{0, n}=\operatorname{Vol}(\sigma)\left(w\left(\tau_{n}\right)-w\left(\tau_{0}\right)\right)$ holds, where $w\left(\tau_{n_{j}}\right)(j=0,1)$ is the 2-cycle on $\widehat{f}_{n_{j}}\left(\widehat{\Sigma}_{n_{j}}^{b}\right)$ as in Lemma $5.1(2)$. There exists the 2-cycle $S\left(\tau_{n}\right)$ on $\Sigma^{b}$ with respect to $\tau_{n} \bmod \mathcal{H}\left(\widehat{f}_{n}\right)_{\text {tube }}$ satisfying $\widehat{f}_{n *}\left(S\left(\tau_{n}\right)\right)=w\left(\tau_{n}\right)$. Then $\operatorname{straight}\left(\psi_{*}\left(z_{0, n}\right)\right)$ is a locally finite 3 -chain on $M^{\prime}$ with

$$
\partial_{3} \operatorname{straight}\left(\psi_{*}\left(z_{0, n}\right)\right)
$$

$$
=\operatorname{Vol}(\sigma)\left(\operatorname{straight}\left(\psi \circ \widehat{f_{n}}\right)_{*}\left(S\left(\tau_{n}\right)\right)-\operatorname{straight}\left(\psi \circ \widehat{f_{0}}\right)_{*}\left(S\left(\tau_{0}\right)\right)\right)
$$

$$
=\operatorname{Vol}(\sigma)\left(\left(f_{n}^{\prime *}\right)_{*}\left(S\left(\tau_{n}\right)\right)-\left(f_{0}^{\prime *}\right)_{*}\left(S\left(\tau_{0}\right)\right)\right)
$$

Here the equality $\operatorname{straight}\left(\psi \circ \widehat{f}_{n}\right)_{*}\left(S\left(\tau_{n}\right)\right)=\left(f_{n}^{\prime *}\right)_{*}\left(S\left(\tau_{n}\right)\right)$ is proved by the fact that $f_{n}^{\prime *}$ is a piecewise totally geodesic map defined as above. It follows that

$$
\omega_{M^{\prime}}\left(\psi_{*}\left(z_{0, n}\right)\right)=\operatorname{Vol}\left(\operatorname{straight}\left(\psi_{*}\left(z_{0, n}\right)\right)\right)=\operatorname{Vol}(\sigma) \operatorname{Vol}^{\mathrm{bd}}\left(f_{0}^{\prime *}, f_{n}^{\prime *}\right)
$$

Hence we have

$$
\begin{align*}
\omega_{M^{\prime}}\left(\psi_{*}(z(0, n))\right) & =\omega_{M^{\prime}}\left(\psi_{*}\left(z_{0, n}\right)\right)-\omega_{M^{\prime}}\left(\psi_{*}\left(\widehat{a}_{0, n}\right)\right) \\
& \leq \operatorname{Vol}(\sigma) \operatorname{Vol}^{\mathrm{bd}}\left(f_{0}^{\prime *}, f_{n}^{\prime *}\right)+b_{0} \boldsymbol{v}_{3} \tag{6.1}
\end{align*}
$$

Consider any bounded 3-cocycle $\eta$ on $M$ satisfying

$$
\begin{equation*}
\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)=\left[\omega_{M}\right]-\psi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)=[\eta] \quad \text { in } H_{b}^{3}(M, \mathbb{R}) \tag{6.2}
\end{equation*}
$$

Then there exists a bounded 2-cochain $c \in C_{b}^{2}(M)$ with $\omega_{M}-\psi^{*} \omega_{M^{\prime}}+\delta^{2} c=\eta$.
Let $\mathcal{E}^{\prime b}$ be the end of $E^{\prime}$ with respect to $\varphi\left(C_{*}\right)$ which corresponds to $\mathcal{E}^{b}$ via $\varphi$. Suppose that $\mathcal{E}^{\prime b}$ were either geometrically finite or non-genuine or a simply degenerate end with ending lamination different from the ending lamination $\nu$ of $\mathcal{E}$. Since $\nu$ is a connected full lamination of $\Sigma^{b}$, if necessary passing to a subsequence, we may assume that $\left\{f_{n}^{\prime *}\right\}$ either converges uniformly to a pleated map $f_{\infty}^{\prime *}: \Sigma^{b} \longrightarrow$ $M^{\prime}$ realizing $\nu$ or diverges to an end of $M^{\prime}$ opposite to $\mathcal{E}^{\prime}$. In either case, $B=$ $\sup \left\{\operatorname{Vol}^{\text {bd }}\left(f_{0}^{\prime *}, f_{n}^{\prime *}\right)\right\}<\infty$. By (6.1) together with Lemma 3.1,

$$
\begin{aligned}
\|\eta\| & \geq \frac{\left(\omega_{M}-\psi^{*} \omega_{M^{\prime}}+\delta^{2} c\right)(z(0, n))}{\|z(0, n)\|} \\
& \geq \frac{\operatorname{Vol}(\sigma)\left(\operatorname{Vol}\left(E^{\mathrm{b}}\left(\widehat{f_{0}}, \widehat{f}_{n}\right)\right)-B\right)-b_{0} \boldsymbol{v}_{3}-8\|c\| v_{0}(2)}{\operatorname{Vol}\left(E^{b}\left(\widehat{f}_{0}, \widehat{f}_{n}\right)\right)}
\end{aligned}
$$

Since $\lim _{n \rightarrow \infty} \operatorname{Vol}\left(E^{b}\left(\widehat{f_{0}}, \widehat{f_{n}}\right)\right)=\infty$, we have $\|\eta\| \geq \operatorname{Vol}(\sigma)$ and hence $\|\eta\| \geq \boldsymbol{v}_{3}$ by letting $\operatorname{Vol}(\sigma) \rightarrow \boldsymbol{v}_{3}$. Since $\eta$ is any element of $Z_{b}^{3}(M)$ satisfying (6.2), it follows that $\left\|\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\| \geq \boldsymbol{v}_{3}$. This contradicts ( 0.2 ). Thus $\mathcal{E}^{\prime \prime}$ must be a simply degenerate end of $M^{\prime}$ with the ending lamination equal to $\nu$ via $\varphi$.
Case 2. $\mathcal{E}^{b}$ has an accidental cusp.
Let $\mathcal{E}_{1}^{b}, \ldots, \mathcal{E}_{k}^{b}(k \geq 2)$ be the genuine sub-ends of $\mathcal{E}^{b}$ and $\nu_{i}(i=1, \ldots, k)$ the ending lamination of $\mathcal{E}_{i}^{b}$. Then $\nu_{1} \cup \cdots \cup \nu_{k}$ is realized as a geodesic lamination in $\Sigma^{b}$. Let $\Lambda^{b}$ be a maximal union of simple closed geodesic in $\Sigma^{b}$ disjoint from $\nu_{1} \cup \cdots \cup \nu_{k}$. Then, for any component $l$ of $\Lambda^{b}, \iota_{n}(l)$ is homotopic to a component of $\widehat{\mathcal{H}}_{n, \text { tube }}$ in $\widehat{\Sigma}_{n}^{b}$ (see Figure 4.3) corresponding to a accidental cusp $V$ of $\mathcal{E}^{b}$ and
hence $V \subset E_{\text {cusp }} \backslash E_{\text {cusp* }}$. From the definition of $E_{\text {cusp* }}, \varphi\left(\iota_{n}(l)\right)$ is realized as a geodesic loop in $E^{\prime b}$. It follows that $\nu_{1} \cup \cdots \cup \nu_{k} \cup \Lambda^{b}$ is a maximal lamination in $\Sigma^{b}$ realized in $E^{\prime b}$. As in Case 1, this gives a contradiction. Thus Case 2 does not occur.

By the results of Cases 1 and 2, we have known that $E_{\text {cusp* }}=E_{\text {cusp }}, E_{\text {cusp* }}^{\prime}=$ $E_{\text {cusp }}^{\prime}$ and any genuine sub-end of $\mathcal{E}$ and the corresponding genuine sub-end of $\mathcal{E}^{\prime}$ are simply degenerate ends with the same ending lamination. Then, by Ending Lamination Theorem [Mi, BCM], $\varphi$ is properly homotopic rel. $M \backslash \operatorname{Int} E$ to a homeomorphism $\varphi_{0}: M \longrightarrow M^{\prime}$ such that $\left.\varphi_{0}\right|_{E}: E \longrightarrow E^{\prime}$ is bi-Lipschitz.

Proof of Theorem C. From our assumption, one can choose the homeomorphism $\varphi: M \longrightarrow M^{\prime}$ so that $\varphi\left(M_{\text {cusp }}\right)=M_{\text {cusp }}^{\prime}$. Let $E$ be a neighborhood of any genuine end $\mathcal{E}$ of $M$. Then $E^{\prime}=\varphi(E)$ is a neighborhood of the genuine end $\mathcal{E}^{\prime}$ of $M^{\prime}$ corresponding to $\mathcal{E}$ via $\varphi$. If both $\mathcal{E}$ and $\mathcal{E}^{\prime}$ are geometrically finite, then it is well known that $\left.\varphi\right|_{E}: E \longrightarrow E^{\prime}$ is properly homotopic rel. $\partial E$ to a bi-Lipschitz map from $E$ to $E^{\prime}$, see for example [Th1, Subsection 8.3] and Epstein-Marden [EM] for more details. So it suffices to consider the case when at least one of $\mathcal{E}$ and $\mathcal{E}^{\prime}$, say $\mathcal{E}$, is simply degenerate. Let $p^{(\prime)}: \widetilde{M}^{(\prime)} \longrightarrow M^{(\prime)}$ be the covering associated with $\pi_{1}\left(E^{(\prime)}\right) \subset \pi_{1}\left(M^{(\prime)}\right)$ and $\widetilde{\varphi}: \widetilde{M} \longrightarrow \widetilde{M^{\prime}}$ a lift of $\varphi$. Then $\widetilde{M^{(\prime)}}$ has a submanifold $\widetilde{E}^{(\prime)}$ such that the restriction $\left.p^{(\prime)}\right|_{\left.\tilde{E}^{\prime \prime}\right)}$ is an isometry onto $E^{(\prime)}$. Since $p^{*}\left(\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right)=\left[\omega_{\widetilde{M}}\right]-\widetilde{\varphi}^{*}\left(\left[\omega_{\widetilde{M}^{\prime}}\right]\right)$, by $(0.2)$

$$
\left\|\left[\omega_{\widetilde{M}}\right]-\widetilde{\varphi}^{*}\left(\left[\omega_{\widetilde{M}^{\prime}}\right]\right)\right\| \leq\left\|\left[\omega_{M}\right]-\varphi^{*}\left(\left[\omega_{M^{\prime}}\right]\right)\right\|<\boldsymbol{v}_{3}
$$

By applying Theorem A to the genuine ends of $\widetilde{M}$ and $\widetilde{M_{\widetilde{E}}^{\prime}}$ adjacent to $\widetilde{E}$ and $\widetilde{E}^{\prime}$ respectively, $\left.\widetilde{\varphi}\right|_{\widetilde{E}}: \widetilde{E} \longrightarrow \widetilde{E}^{\prime}$ is properly homotopic rel. $\partial \widetilde{E}$ to a bi-Lipschitz map and hence $\left.\varphi\right|_{E}: E \longrightarrow E^{\prime}$ is so rel. $\partial E$. Combining these facts, one can show that $\varphi$ is properly homotopic to a bi-Lipschitz map.

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