

Table 1: Fundamental operations on discrete convex functions

Discrete convexity	Variables		Restriction	Projection	Addition		Convolution		Reference
	Permut.	Scaling			$f + \varphi$	$f_1 + f_2$	$f \square \varphi$	$f_1 \square f_2$	
Separable conv	Y	Y	Y	Y	Y	Y	Y	Y	
Integrally conv	Y	N	Y	Y	Y	N	Y	N	[10, 11, 19]
L^h -convex	Y	Y	Y	Y	Y	Y	Y	N	[14]
L-convex	Y	Y	N	Y	Y	Y	Y	N	[14]
M^h -convex	Y	N	Y	Y	Y	N	Y	Y	[14]
M-convex	Y	N	Y	N	Y	N	Y	Y	[14]
Multimodular	N	Y: Prop.7 Y*:Prop.6 alt. proof	alt. proof	N	Y	Y	N	N	[1] this paper [6] this paper
Globally d.m.c.	Y	Y	Y	Y	Y	Y	N	N	[12]
Locally d.m.c.	Y	Y	Y	Y	Y	Y	N	N	[12]
M-conv (jump)	Y	N	Y	Y	Y	N	Y	Y	[7, 16]

d.m.c.: discrete midpoint convex,

φ : separable convex

Y: Discrete convexity (of that kind) is preserved, N: Not preserved

Y*: Discrete convexity (of that kind) is preserved in some cases

A recurrence formula consists of various kinds of operations, some of which preserve multimodularity and others not. The projection operation (partial minimization) is closely related to the Bellman equation in dynamic programming, and the assumption of U being an interval (consecutive variables) in Proposition 10 is quite natural in this interpretation. The reversal of the ordering of variables in Proposition 6 corresponds to the reversal of “time” in recurrence relations. It is hoped that the results of this paper will find applications in concrete problems in operations research.

The known facts about fundamental operations on discrete convex functions, including those obtained in this paper, are summarized in Table 1.

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