

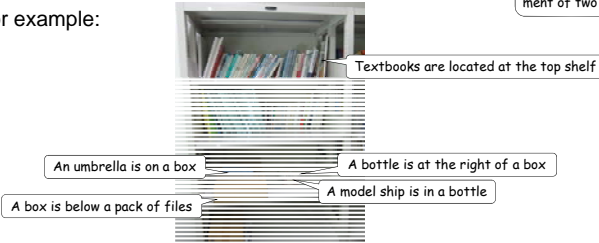
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Research Goal

To propose a set of qualitative spatial relations designed for supporting man-machine communication about object locations in a *cabinet*

For example:



'Planar' storage where we can ignore the front-back arrangement of two different objects

In smart home environment, machines have to communicate such 'positioning expressions' with ordinary people.



But why do we consider a new set of relations, instead of using a existing sets of topological relations and directional relations?

Reason 1

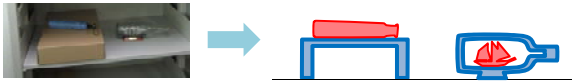
Existing direction models distinguish huge number of relations:
 • Papadias & Sellis [1] → 69 relations
 • Cicerone & Felice [2] → 218 relations
 • Kurata & Shi [3] → 222 relations

Reason 2

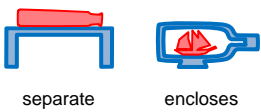
Topological relations [4-5] are based on *partonomy* and *connectivity*, but partonomy does not hold between physical objects
 • Portland is *in* Oregon (partonomy)
 • An model ship *in* a bottle (not partonomy)

Our Model

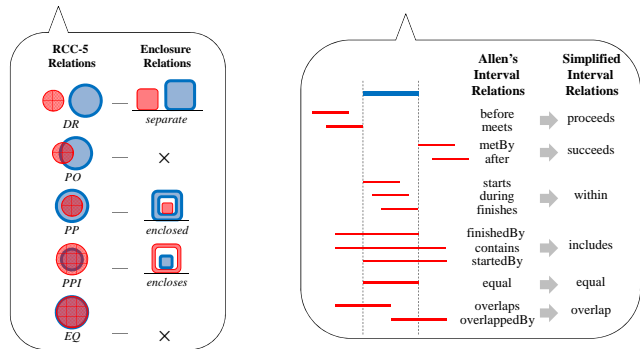
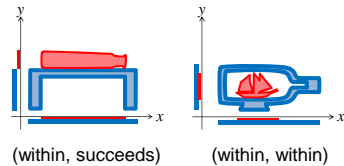
First, we consider the cross-section of objects.



To capture topological characteristics, we consider *enclosure relations*, which correspond to RCC-5 relations [5].



To capture directional characteristics, we consider simplified version of Allen's interval relations [6] on x- and y-axes.



Finally, we combine the enclosure relation and the pair of interval relations.

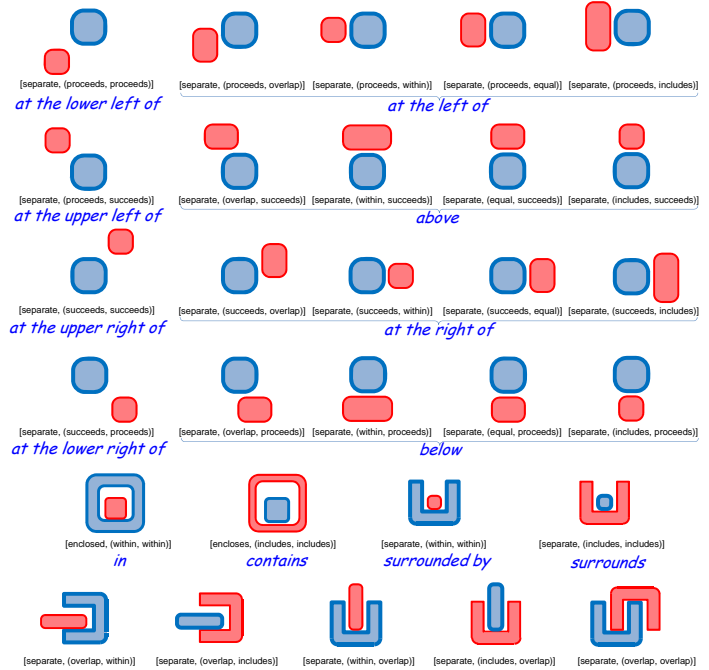


[separate, (within, succeeds)] [encloses, (within, within)]

These relations are called *cabinet relations*.

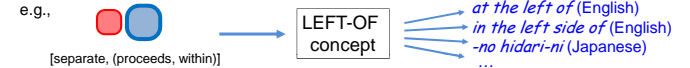
Possible Relations and Expressions

Even though we can consider $3 \times 6 \times 6 = 108$ cabinet relations, **only 29 relations** are possible in the real world:



As shown above, most of the 29 cabinet relations can be mapped to simple positioning expressions in English.

For generality, we can consider an intermediate use of ontological concepts:



Reasoning on Cabinet Relations

Converse of a cabinet relation can be derived by combining the converse of each element.

$$e.g., r(A, B) = [separate, (precedes, within)] \rightarrow r(B, A) = [separate, (succeeds, includes)]$$

Similarly, compositions of two cabinet relations can be derived by combining the composition of each element pair.

$$e.g., r(A, B) = [separate, (precedes, within)] \rightarrow r(A, C) = [separate, (precedes, *)]$$

$$r(B, C) = [encloses, (includes, includes)]$$

Composition table of the enclosure relations				Composition table of the simplified interval relations					
	separate	enclosed	encloses	precedes	succeeds	within	includes	equal	overlap
separate	+	separate.enc/enclosed	separate	precedes	+	within	includes	equal	overlap
enclosed	separate	+	enclosed	precedes	precedes	within	includes	equal	overlap
encloses	separate.encloses	enclosed.enc/encloses	+	precedes	precedes	within	includes	equal	overlap
precedes	precedes	precedes	precedes	+	succeeds	within	includes	equal	overlap
succeeds	precedes	precedes	precedes	succeeds	+	within	includes	equal	overlap
within	precedes	precedes	precedes	within	within	+	includes	equal	overlap
includes	precedes	precedes	precedes	within	within	includes	+	equal	overlap
equal	precedes	precedes	precedes	within	within	includes	includes	+	overlap
overlap	precedes	precedes	precedes	within	within	includes	includes	includes	+

Future Work

- To find justification for the proposed mapping between cabinet relations and positioning expressions
- To implement the above idea and test its applicability in a smart home environment

References

[1] Papadias, D., Sellis, T.: Spatial Reasoning Using Symbolic Arrays. In: International Conference GIS (1992)
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 [3] Kurata, Y., Shi, H.: Toward Heterogeneous Cardinal Direction Calculus. In: KI 2009, LNCS 5803, pp. 452-459. (2009)
 [4] Egenhofer, M., Herring, J.: Categorizing Binary Topological Relationships between Regions, Lines and Points in Geographic Databases. In: NCGIA Technical Reports 91-7 (1991)
 [5] Randell, D., Cui, Z., Cohn, A.: A Spatial Logic Based on Regions and Connection. In: Knowledge Representation and Reasoning, 165-176(1992)
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